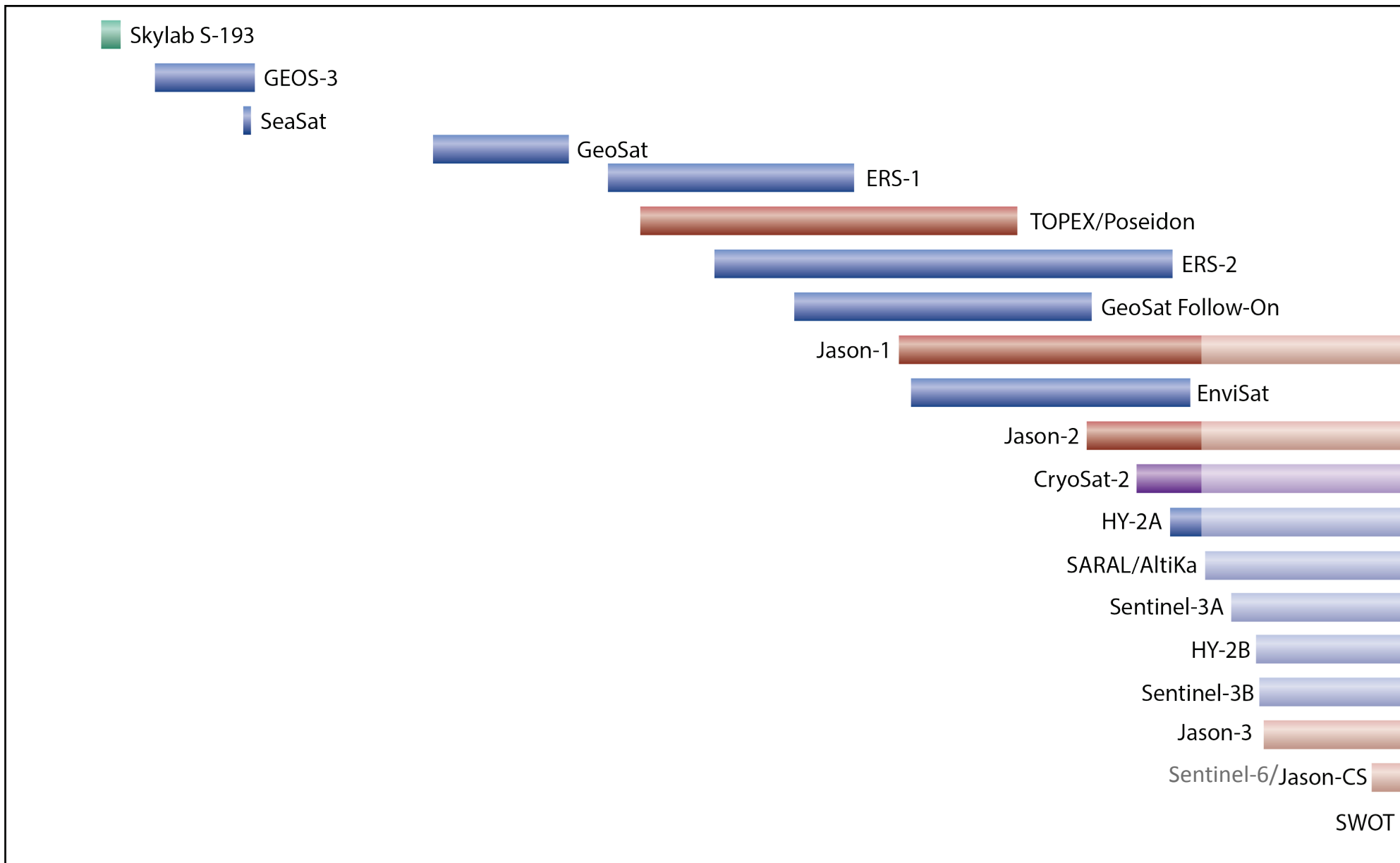


Altimetry: Overview on LR, HR (SAR), SARin, and RDSAR  
Mònica Roca and Richard Francis

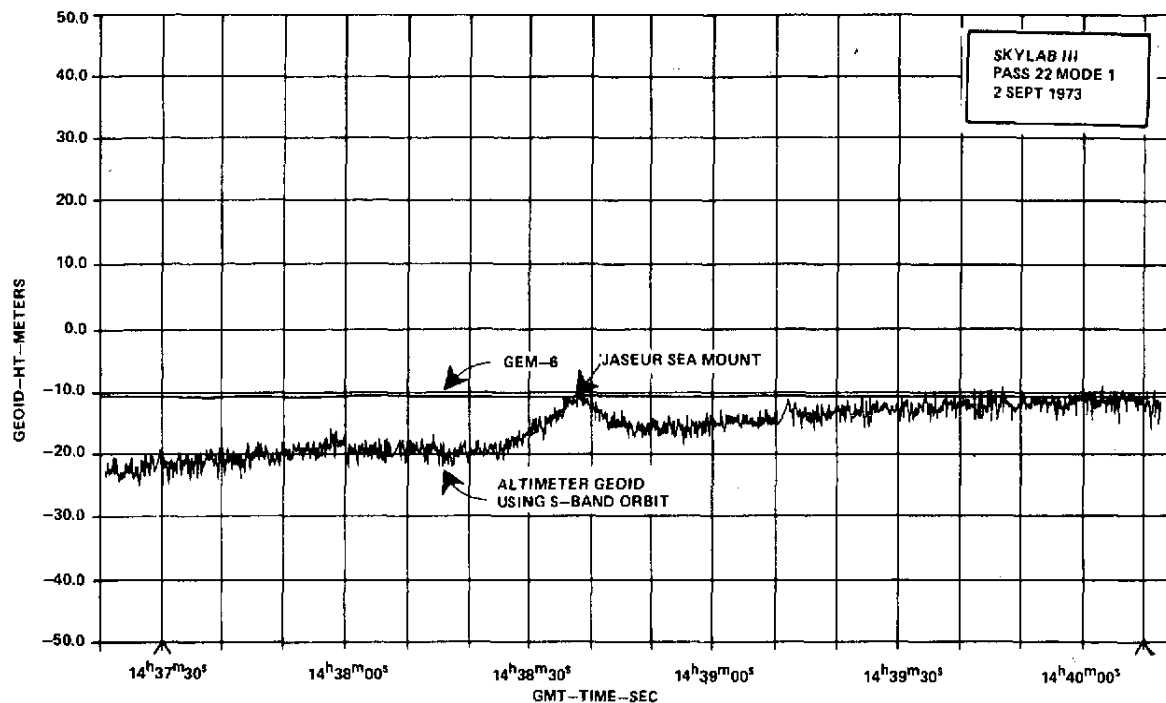
**isardSAT**<sup>®</sup>

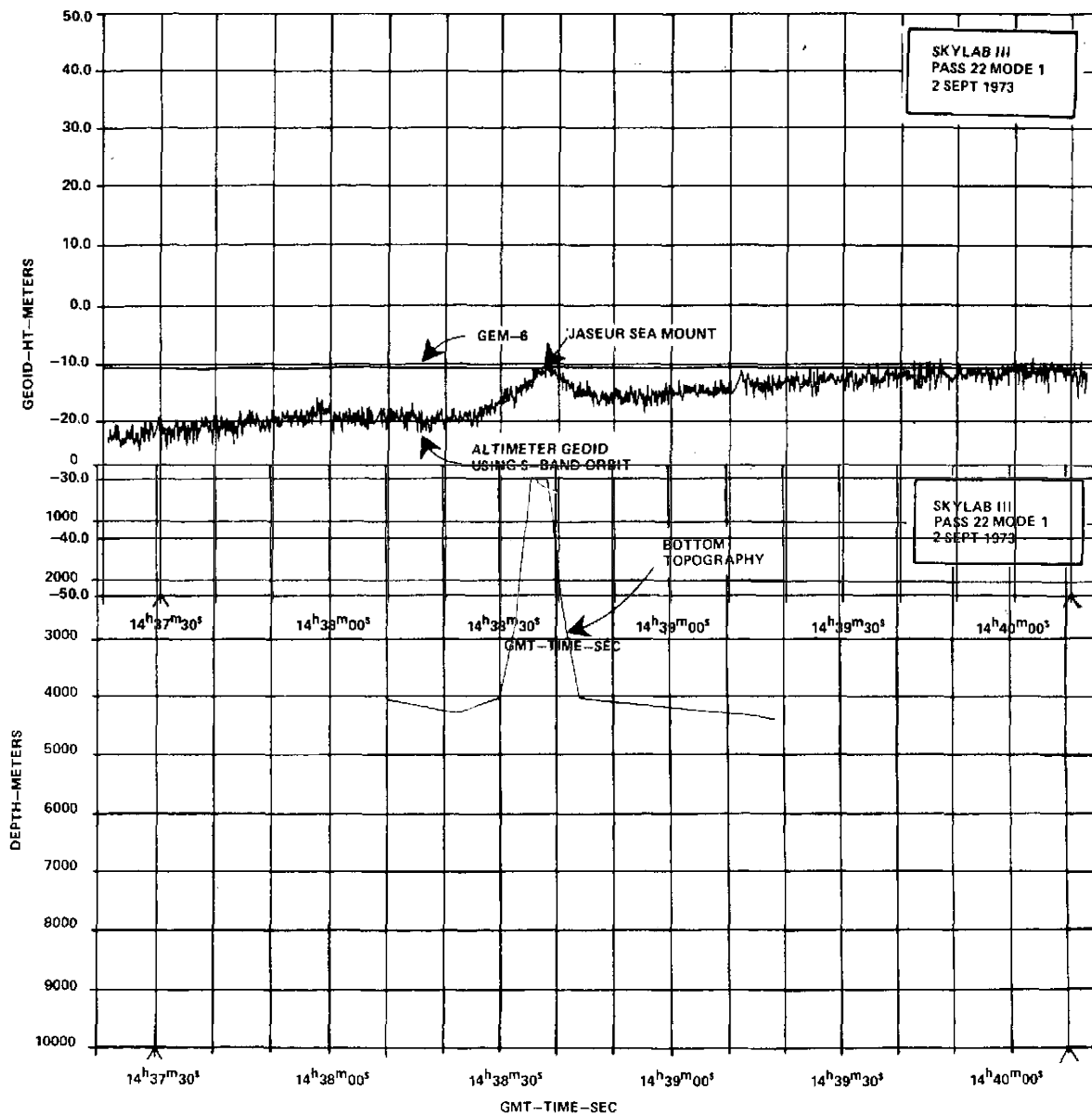


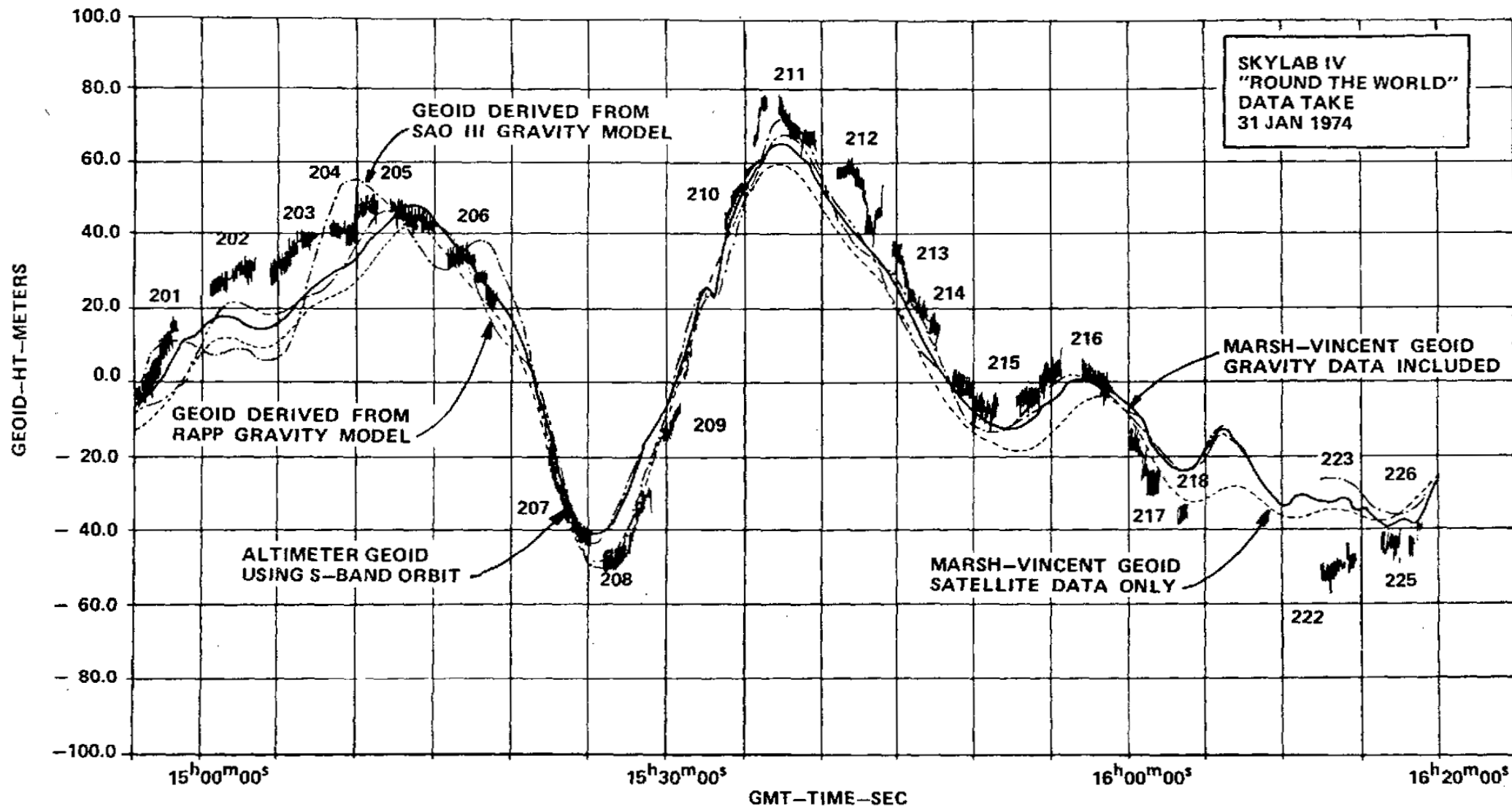


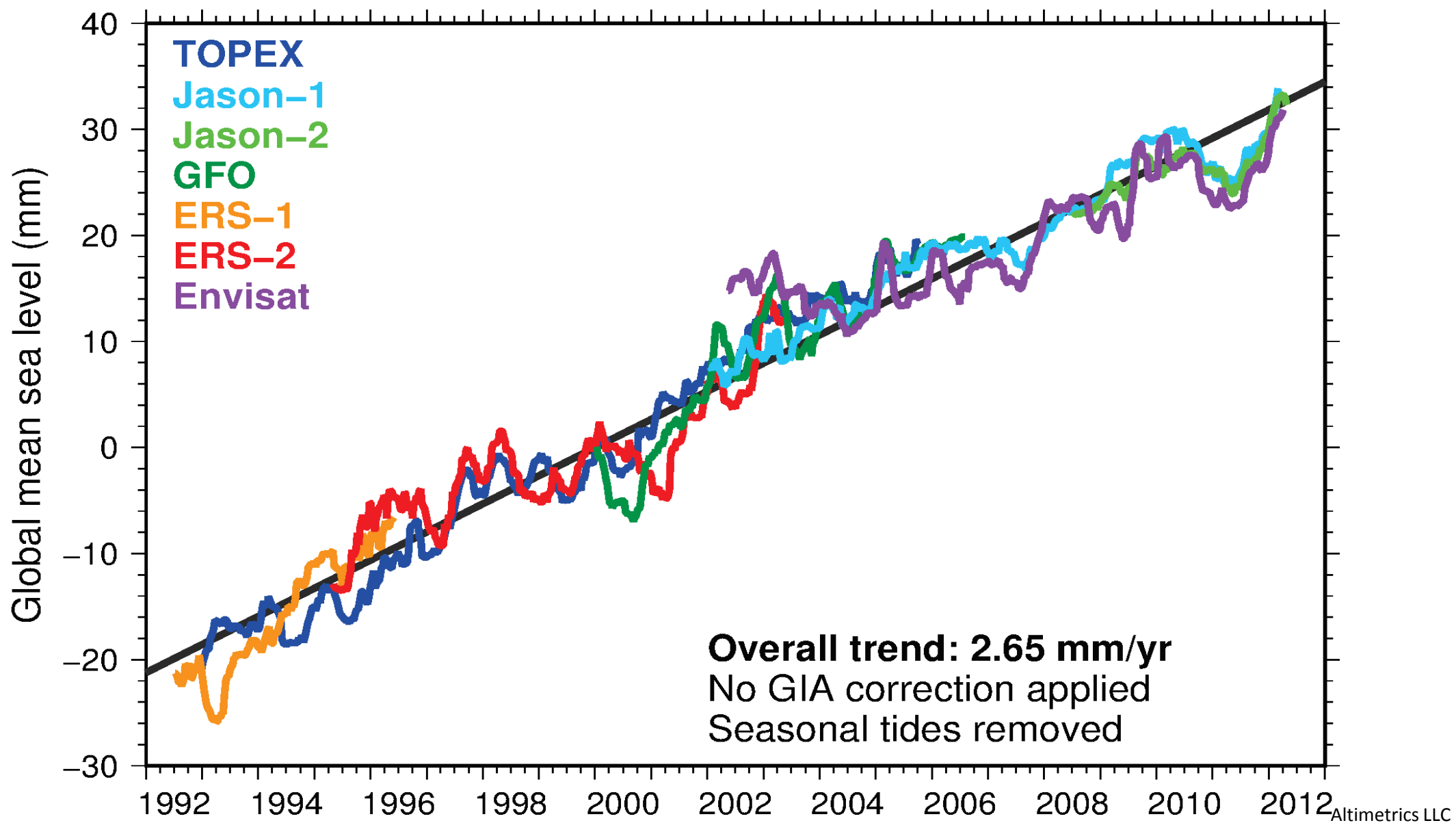
# Why measure altitude from space?

- Altimetry first formulated at Williamstown Conference (1969)
- Need was to make measurements over ocean:
  - To measure gravitational geopotential
  - To measure mean sea-level

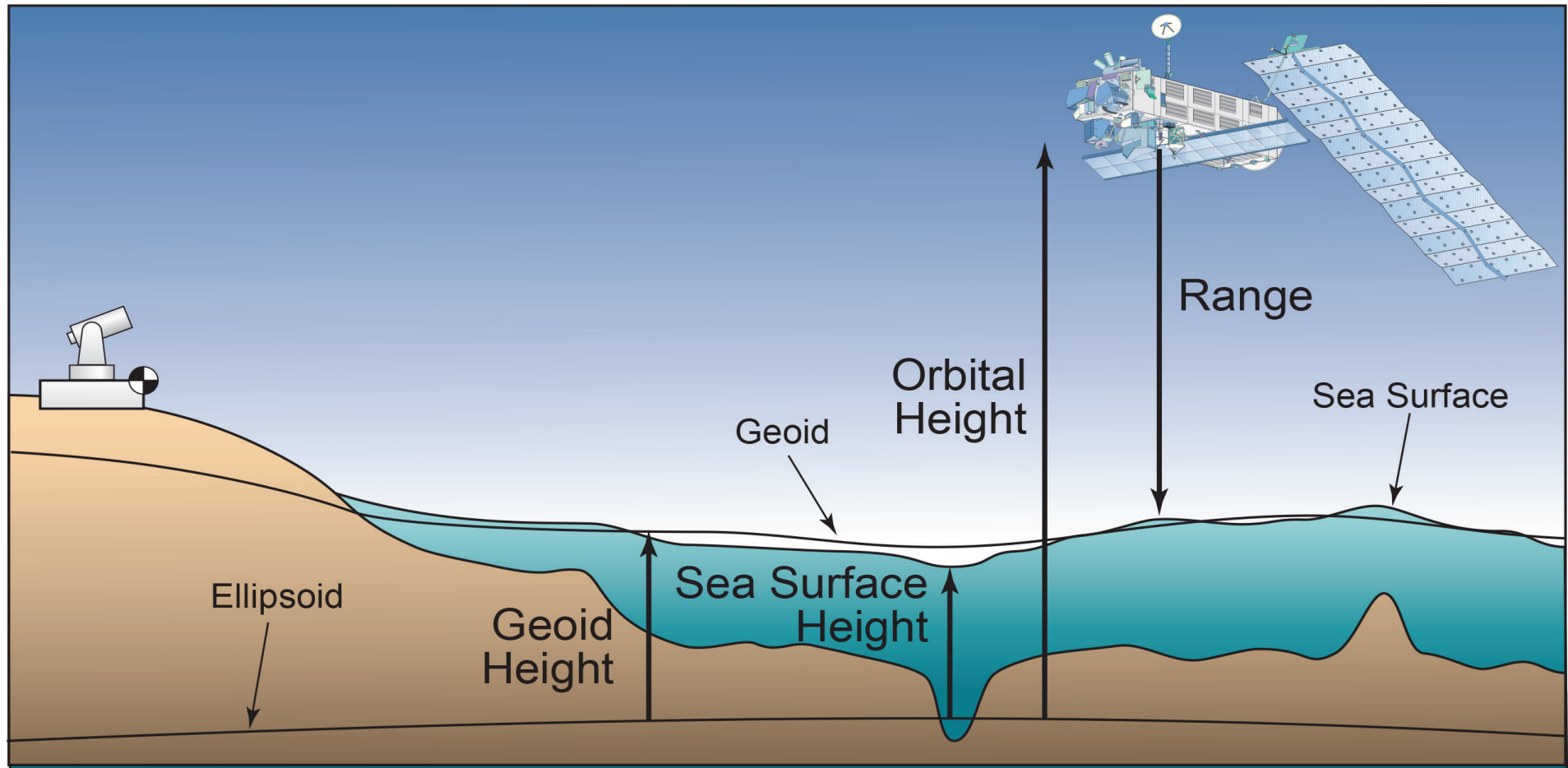








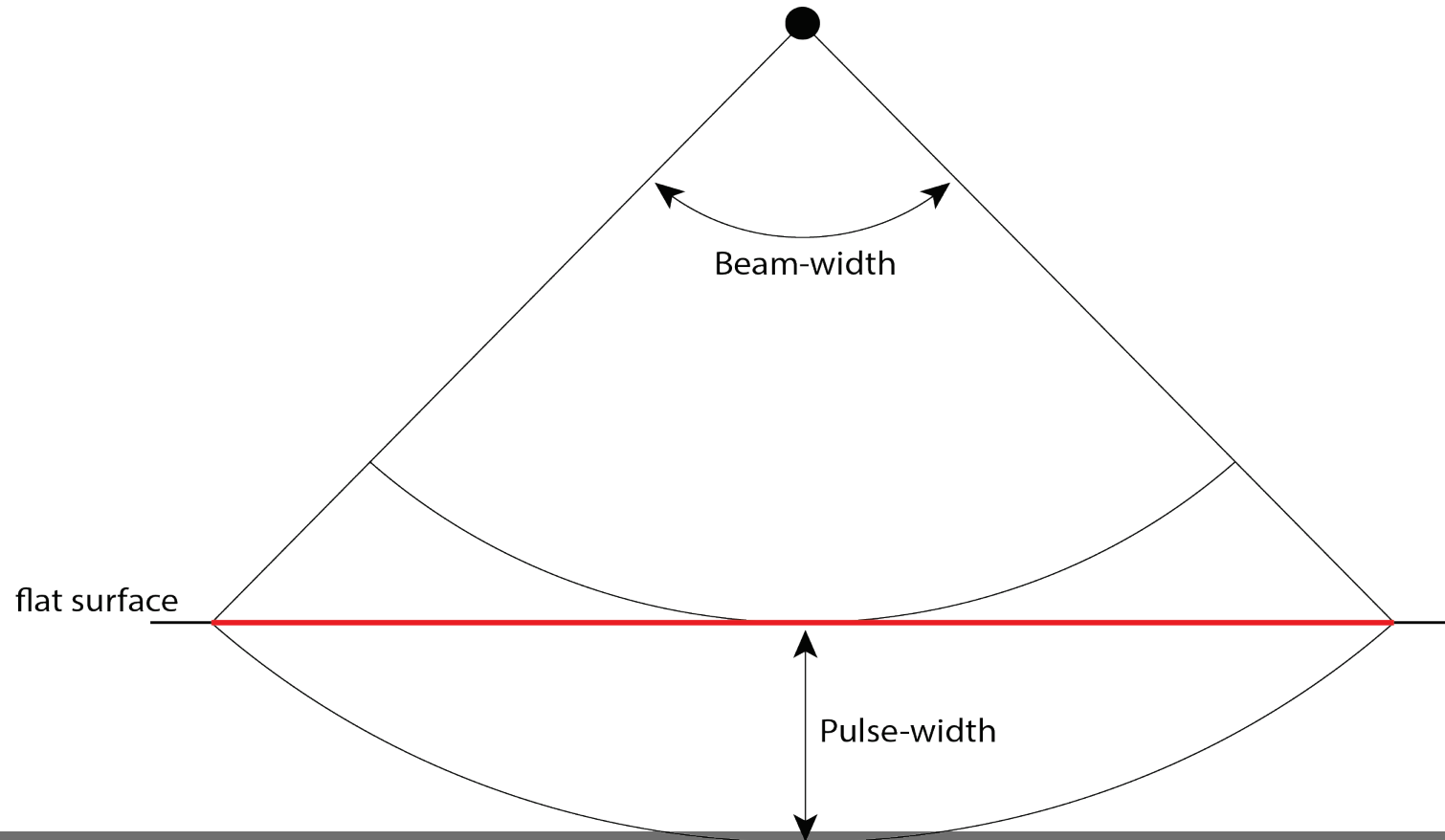




- Williamstown Conference (1969) identified 10 cm as requirement
- Skylab S-193 (1972-74) height noise  $\sim 1$  m
- Gravitational features in the sea surface visible, but no ocean circulation
- More accuracy needed!

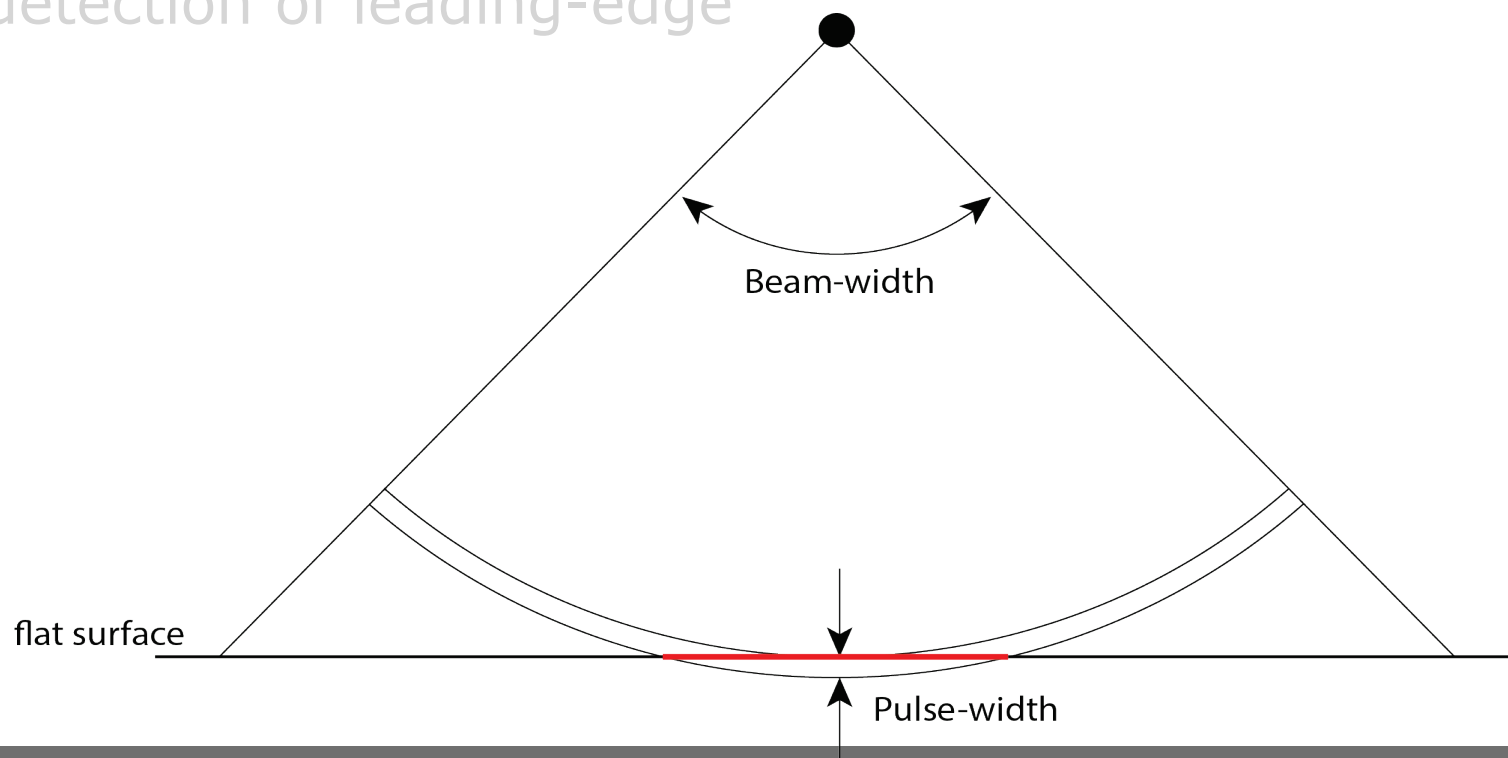
# How it works

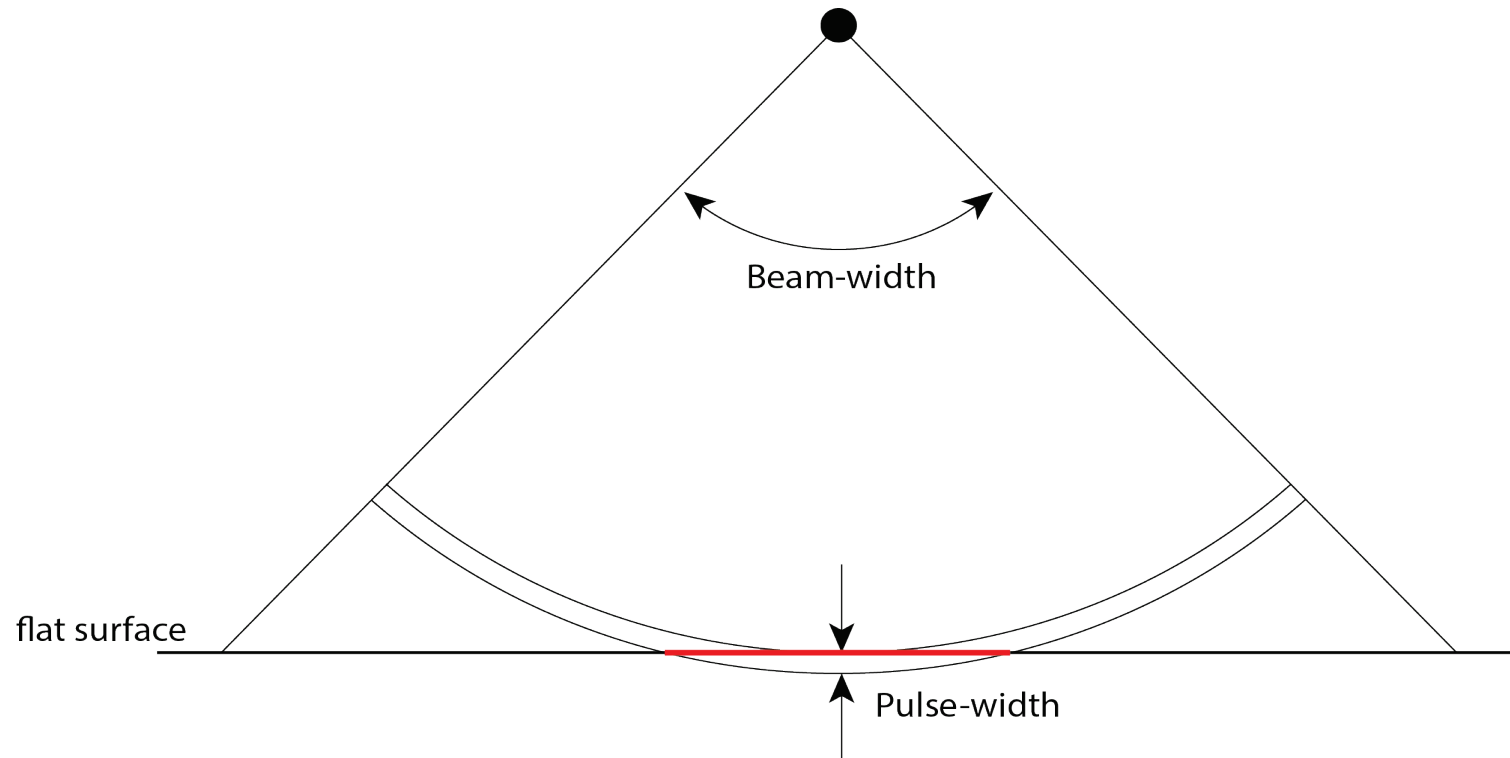
- Beam-width limited geometry (for a flat surface):
  - all surface within beam illuminated simultaneously
  - stringent pointing: pointing errors directly affect footprint location and echo shape
  - narrow antenna beam
  - full echo
  - the laser case



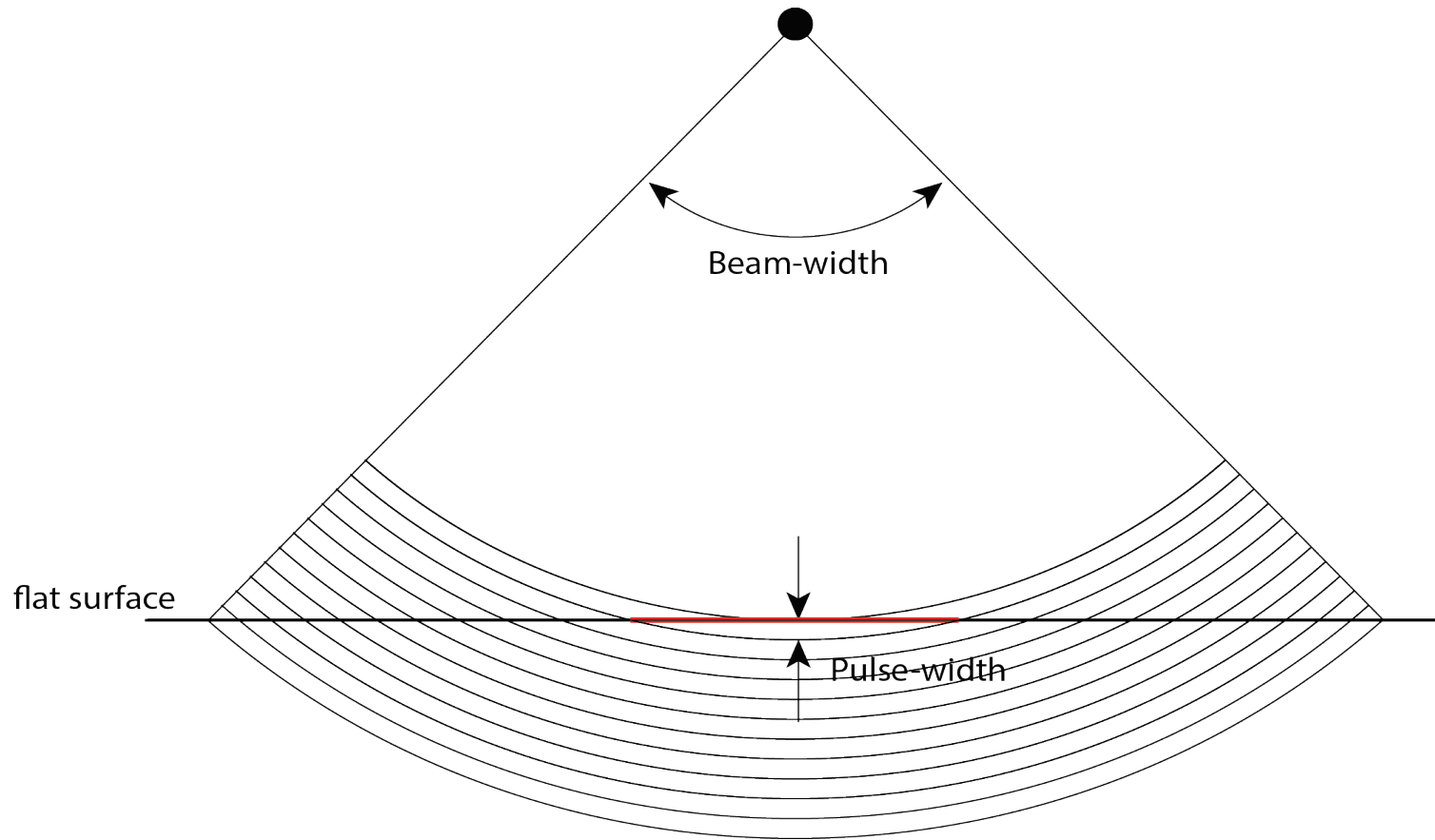
- Pulse-width limited geometry (for a flat surface):
  - “wide” antenna beam: illuminated surface defined by pulse-width
  - pointing errors affect echo shape but not location
  - sensitive to surface geometry
  - detection of leading-edge

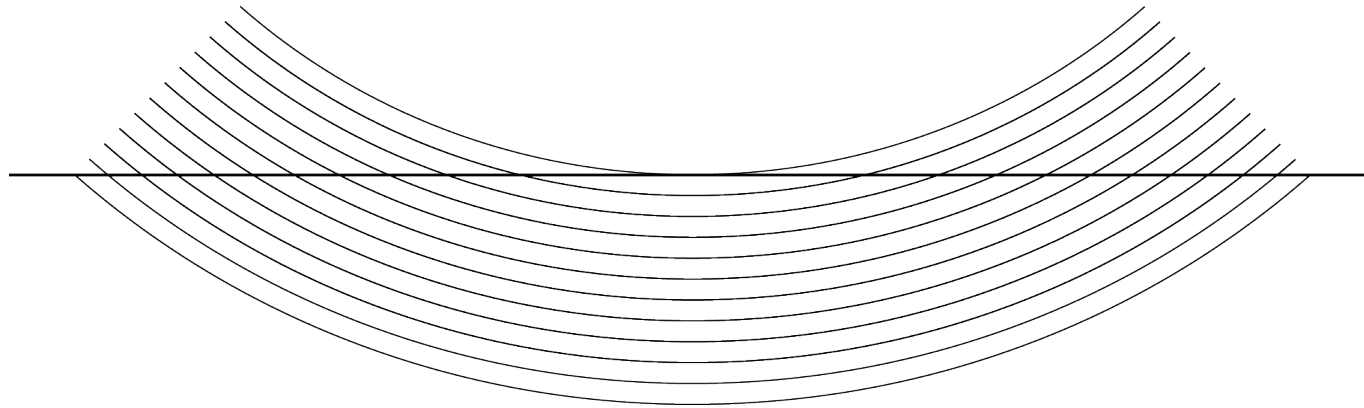
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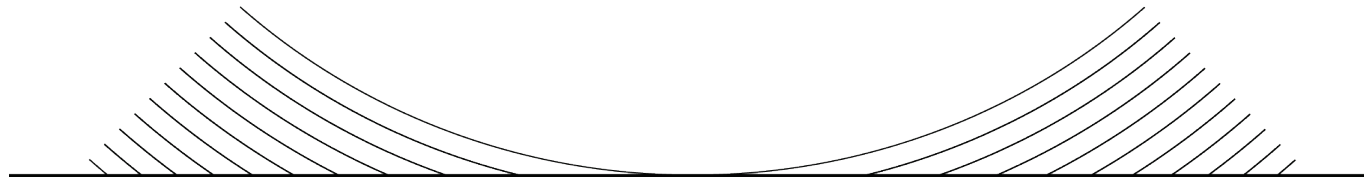


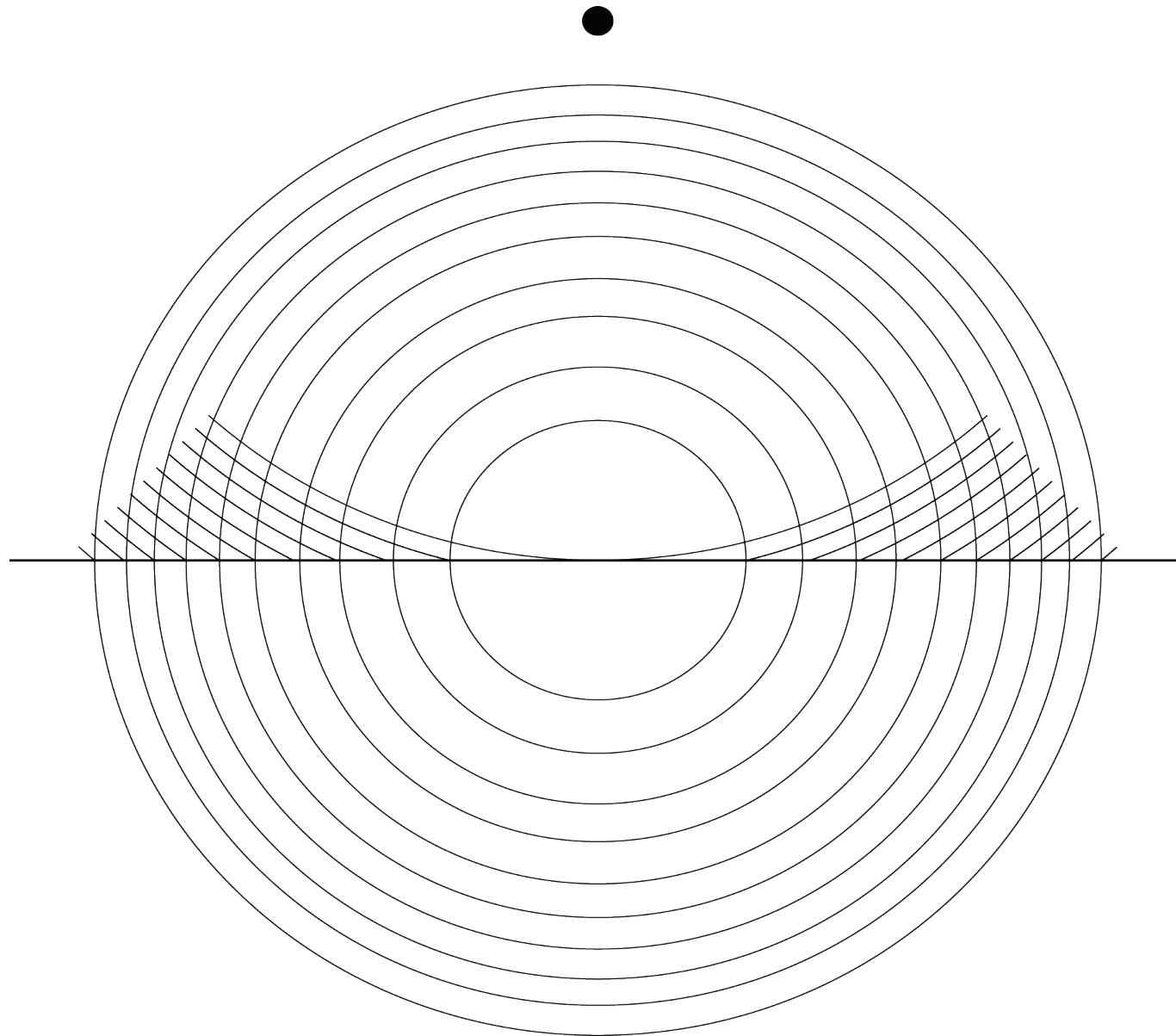


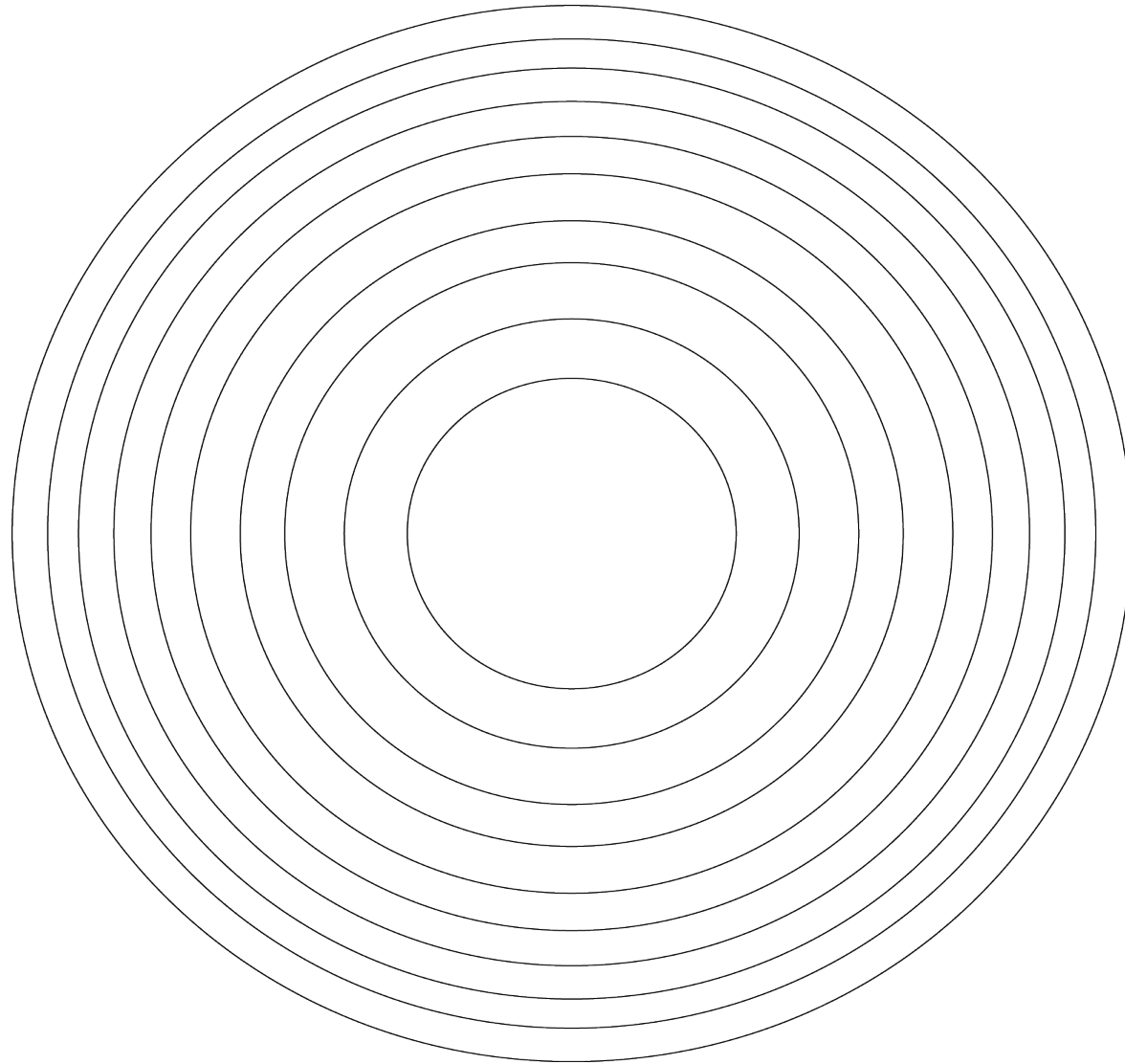


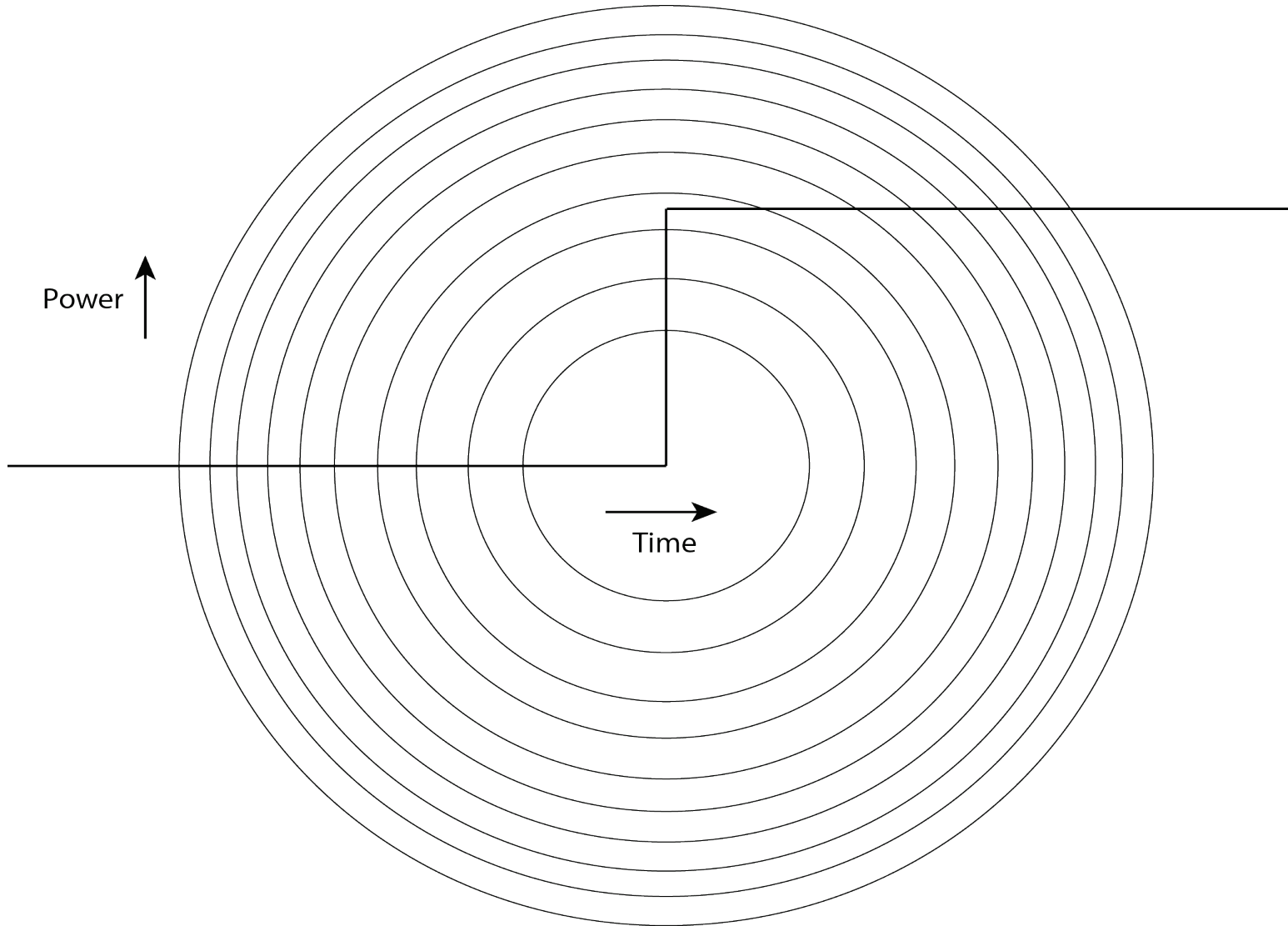


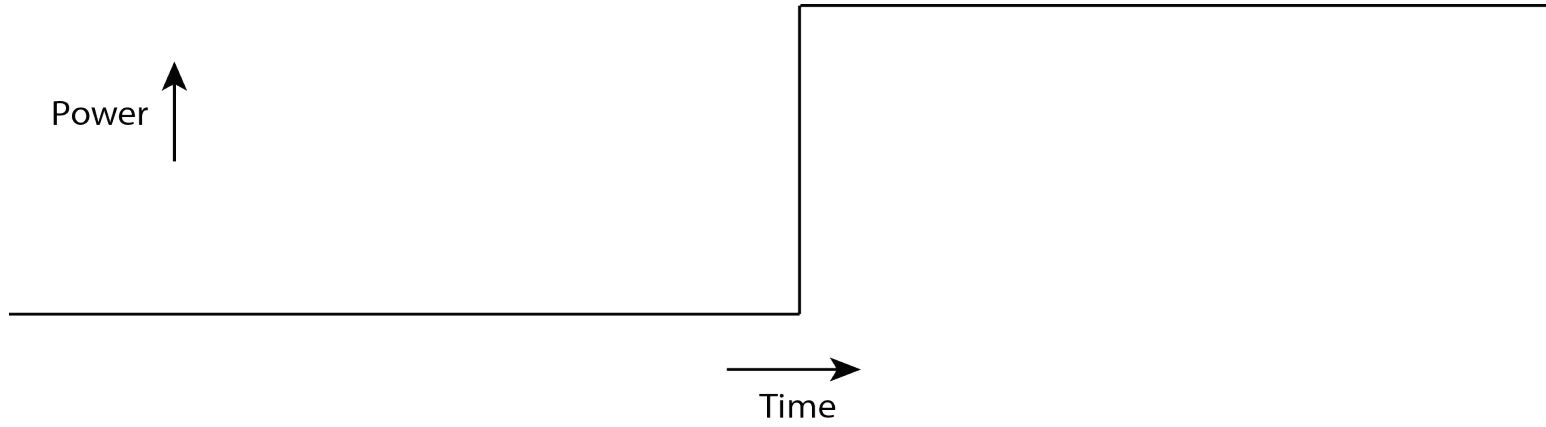


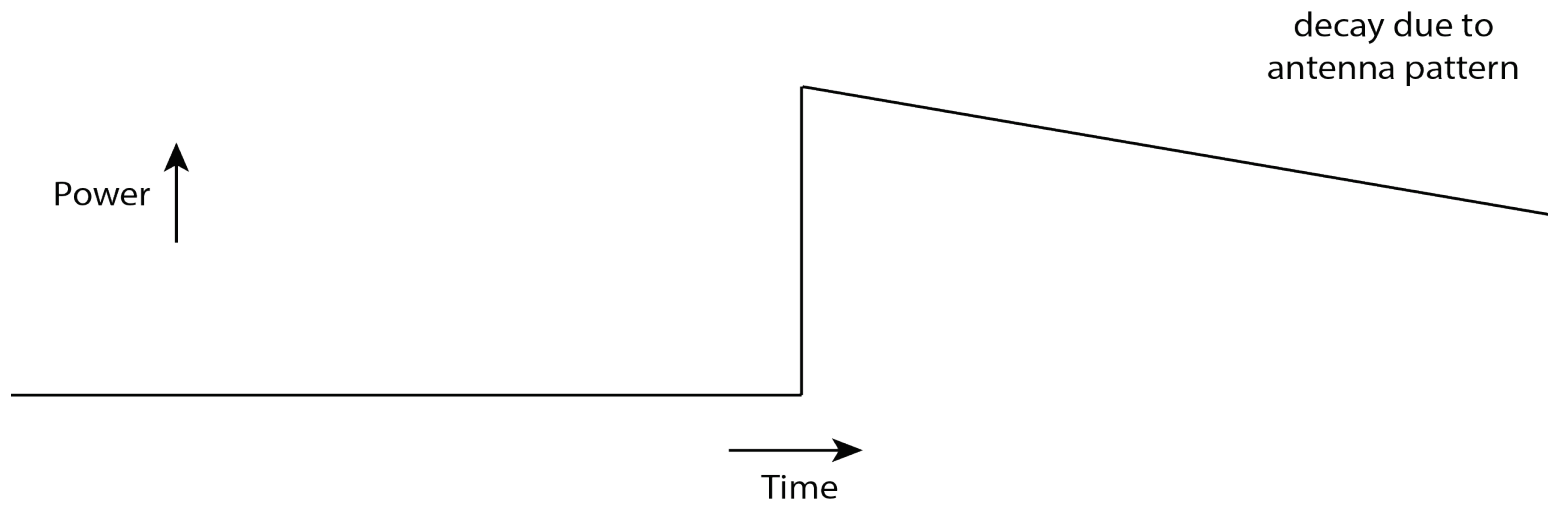




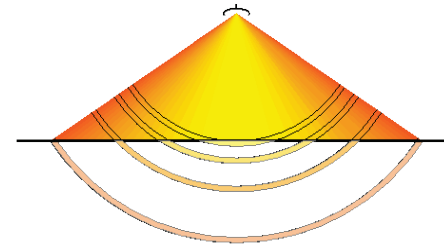




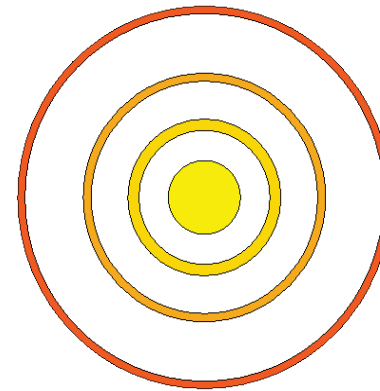




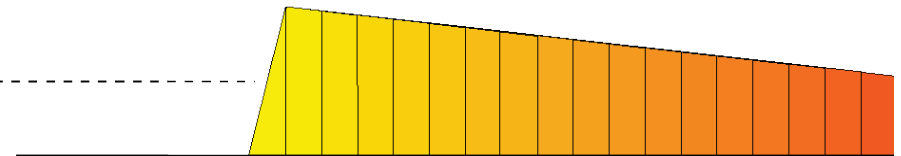
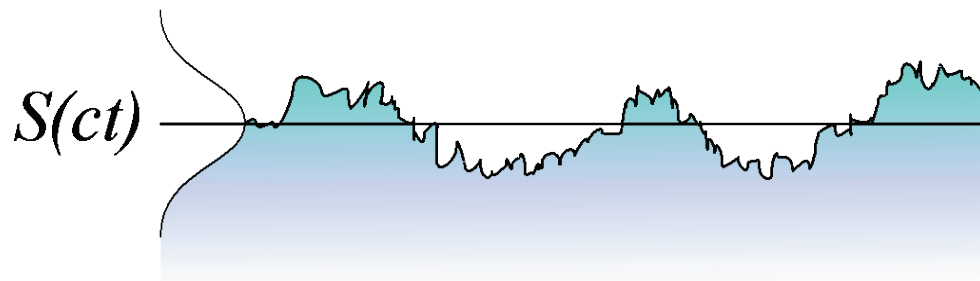


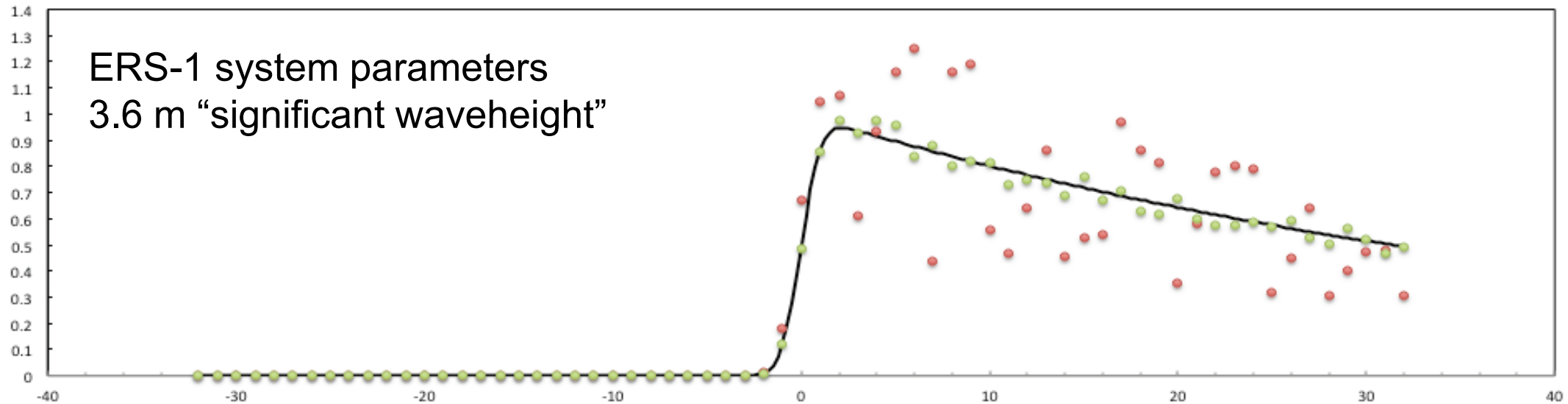


$$P_r(t) = I(t) * S(ct) * P_{fs}(t)$$

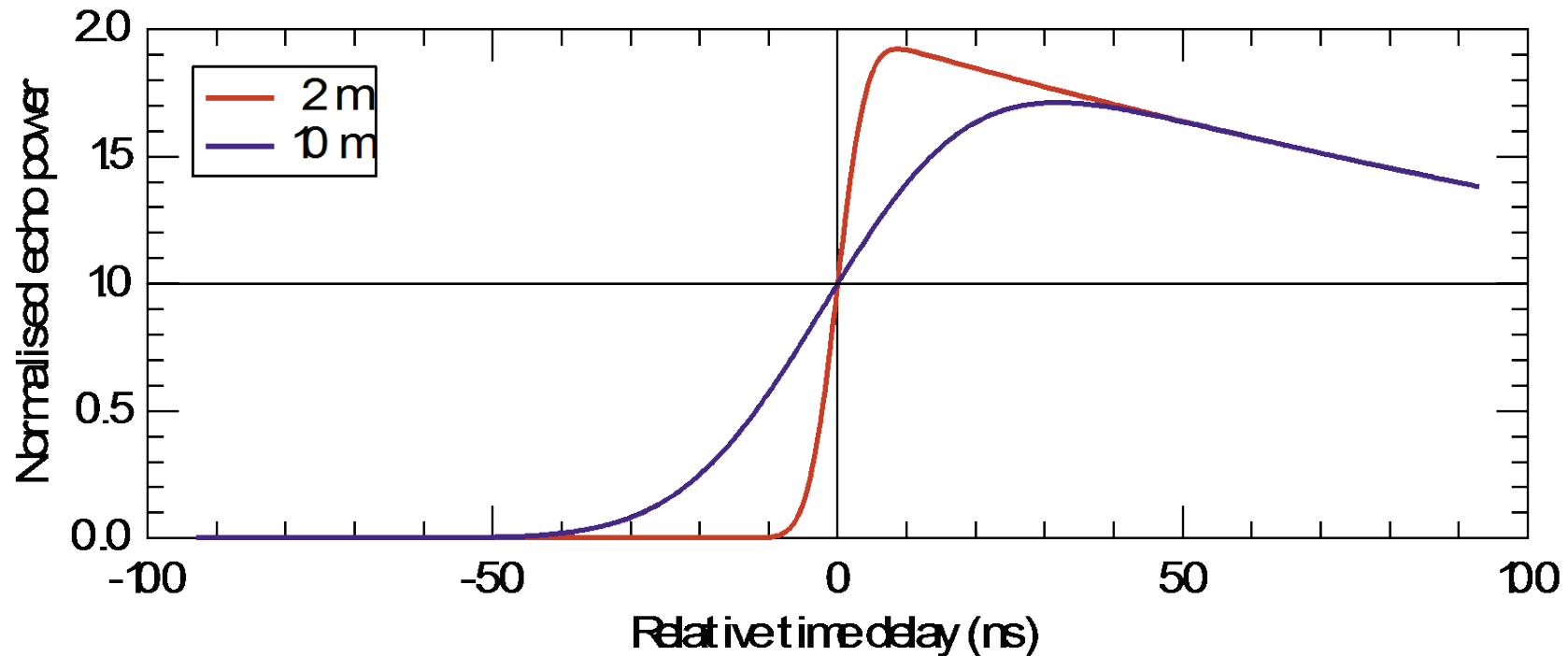


$P_{fs}(t)$





- Black line: average echo
- Red points: individual echo shows **speckle**
- Green points: on-board average of 50 echoes



- A given power point (e.g. 50%, 87%) is related to the echo delay time.
- Leading edge slope is related to Significant Waveheight.
- Integrated echo power is related to surface  $\sigma^{\circ}$ .

- Coherent radiation illuminating a surface which is rough at the wavelength scale produces *speckle* (multiplicative noise).
- Effect of speckle can be reduced by averaging **decorrelated** echoes.
- Height noise normally characterised by averages 1 second for low resolution, 1/20 seconds for high resolution.
- Height noise reduces as more echoes are averaged in a given time.

Pulse Repetition Interval (PRI)  
 Pulse Repetition Frequency (PRF)  
 $PRF = 1/PRI$

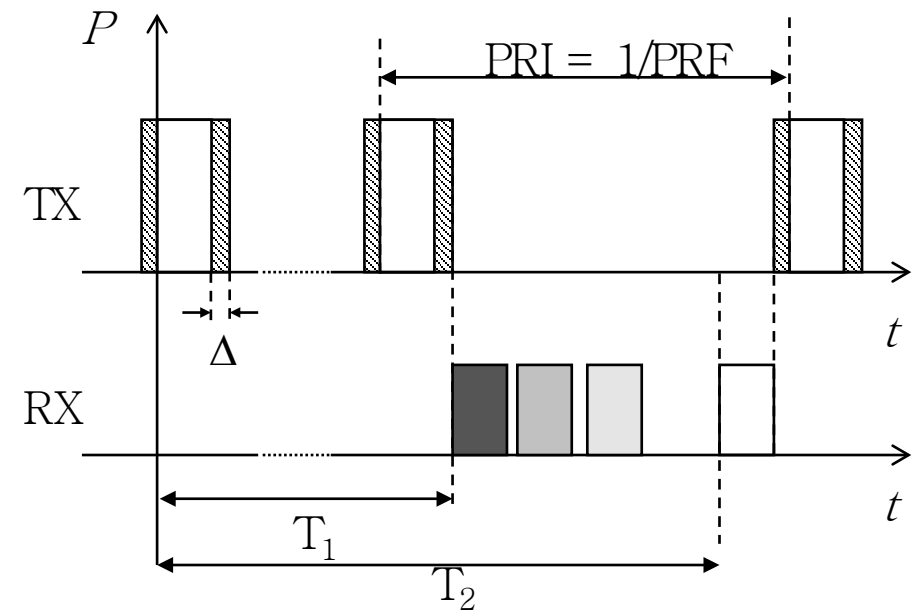
- Higher PRF provides more echoes in a given time.
- limit when echoes become correlated ( $\sim 2$  kHz PRF)

Decorrelation time:

$$PRF \leq \frac{f \cdot v \cdot \sqrt{\tau_c}}{0.305 \cdot \sqrt{ch} \cdot \left(\frac{R+h}{R}\right)}$$

$f$  = radar carrier frequency  
 $v$  = satellite ground-track velocity  
 $R$  = Earth radius  
 $h$  = satellite height

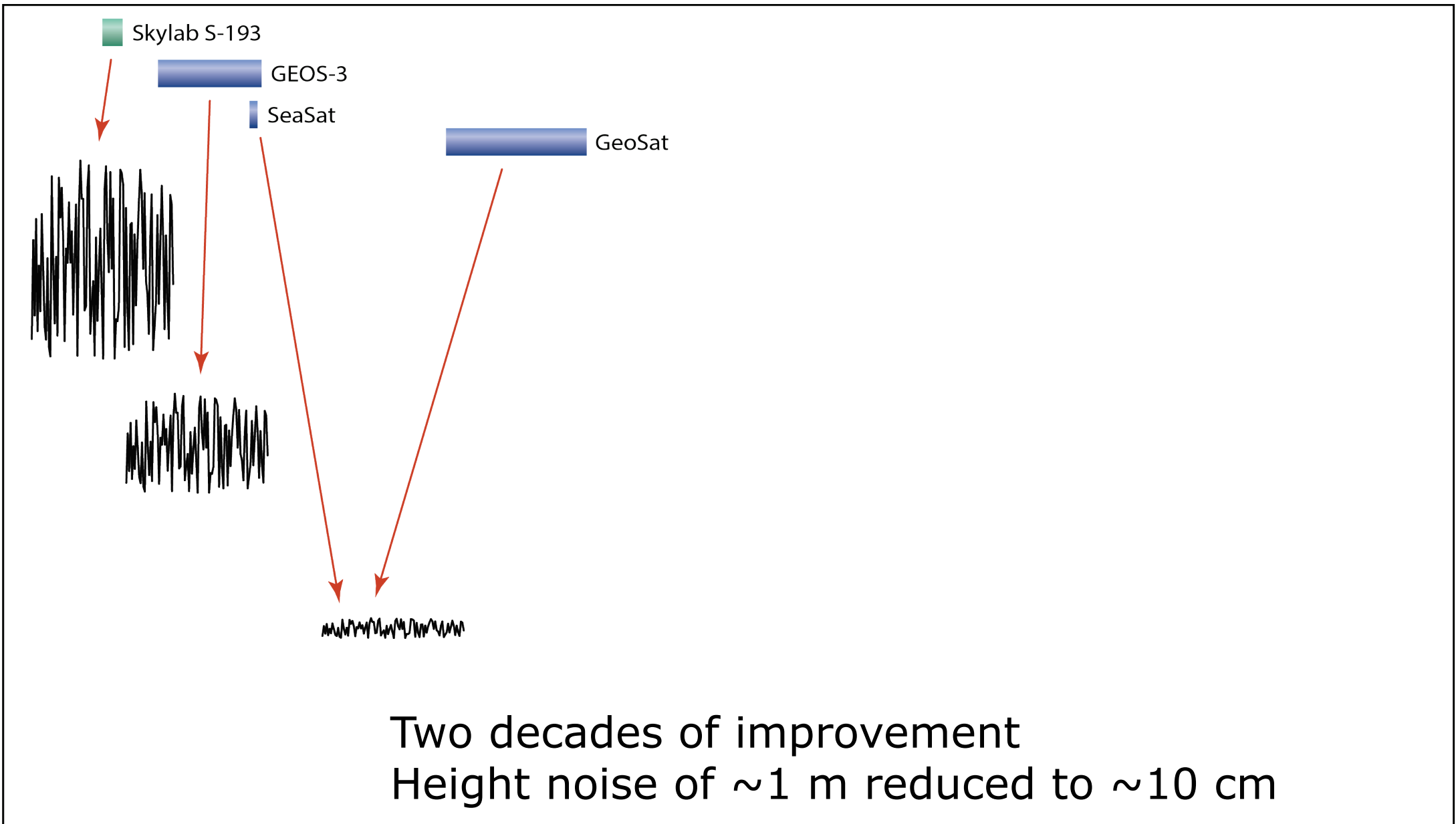
Ambiguity:

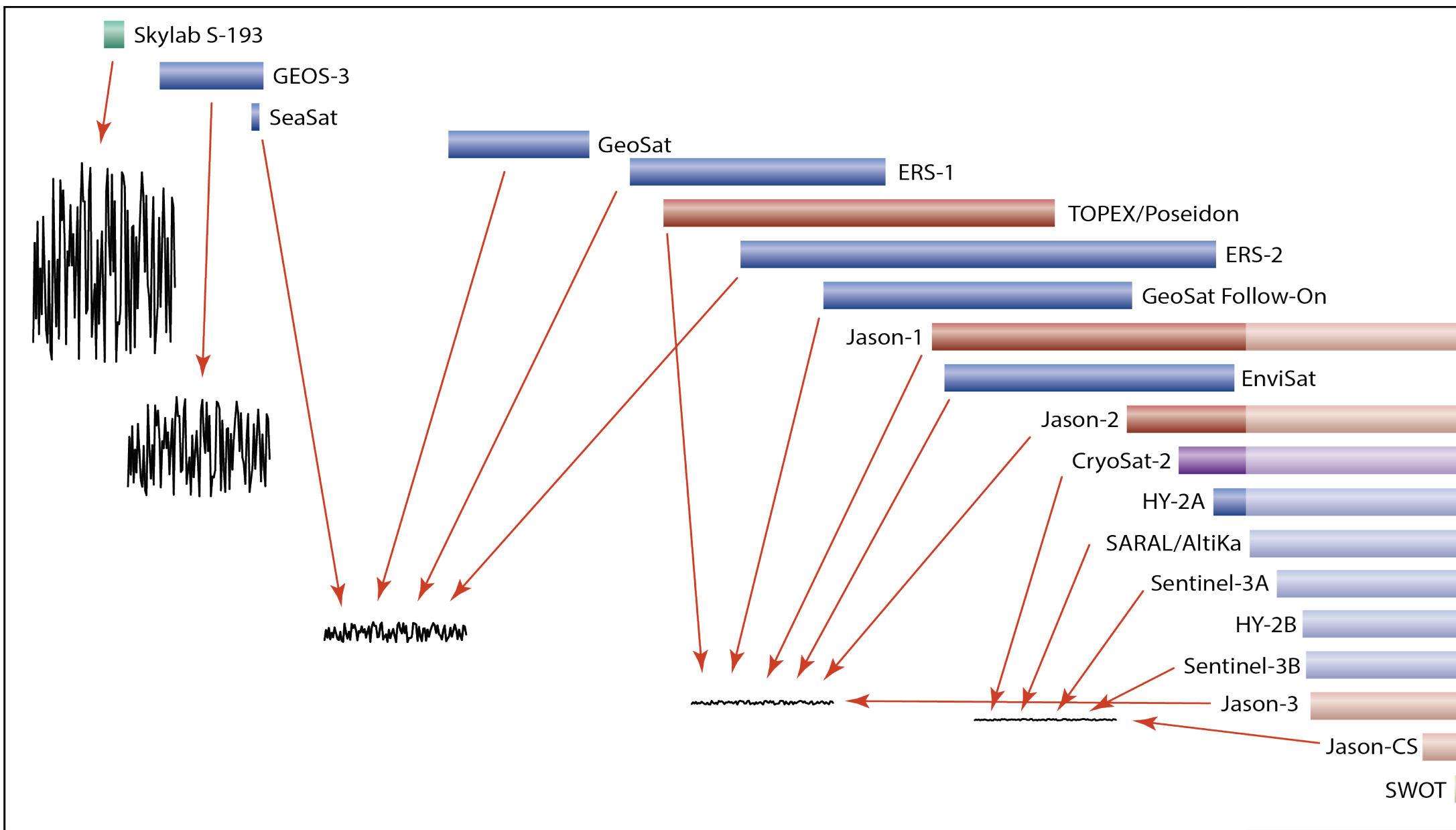


$$T_1 > n \cdot PRI + \tau_u + \Delta$$

$$(n+1) \cdot PRI > T_2 + \tau_u + \Delta$$

$$\therefore PRI > T_2 - T_1 + 2(\tau_u + \Delta)$$





# Technology

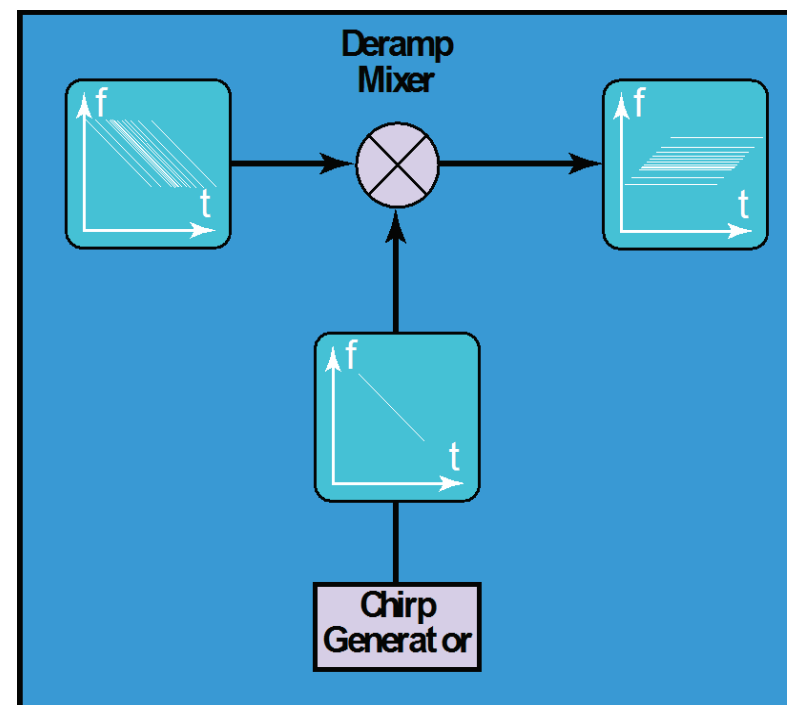
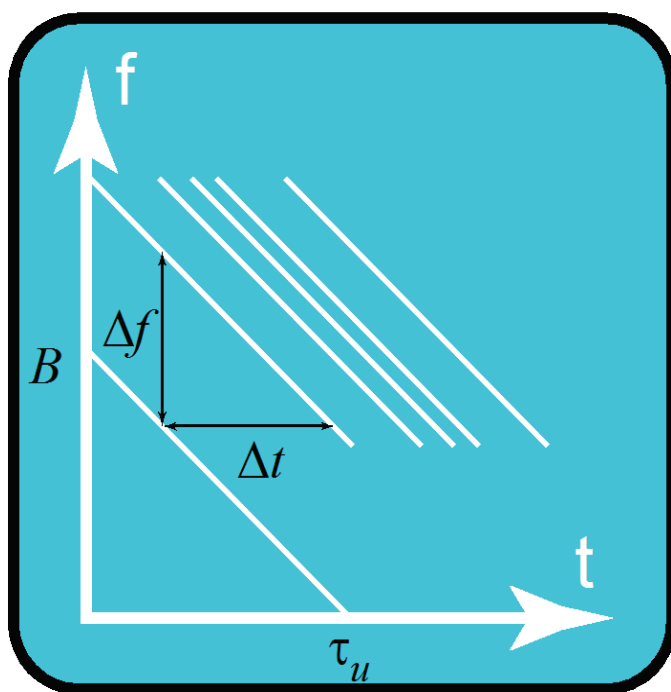


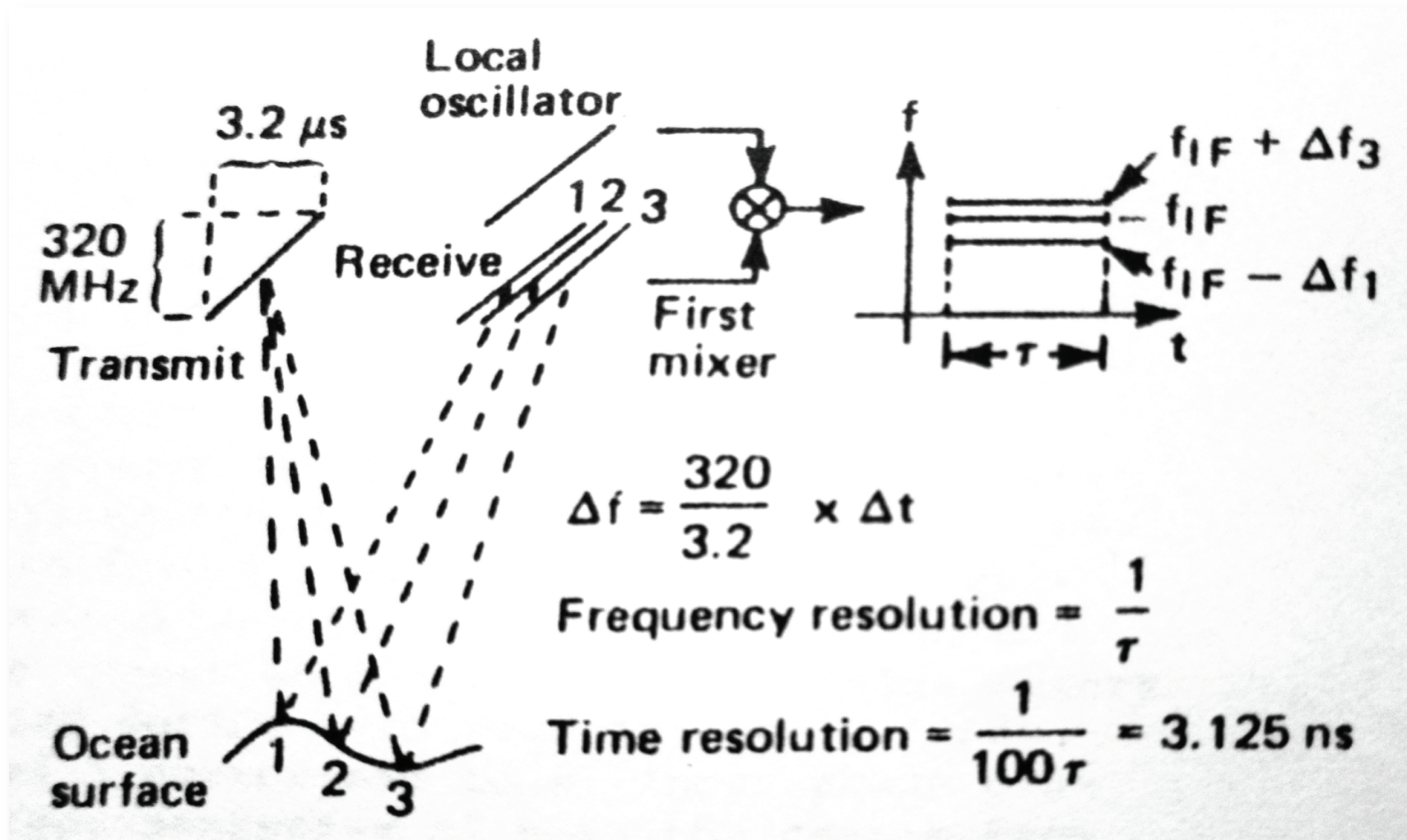
- Skylab S-193 was a conventional pulse radar
  - 100 ns uncompressed pulse (normally)
  - 435 km altitude
  - 250 Hz PRF
- GEOS-3 introduced pulse compression
  - 12.5 ns compressed pulse (compression ratio: 80)
  - 840 km altitude
  - 100 Hz PRF

- Conventional pulse compression radar:
  - Range resolution driven by the bandwidth (B):
  - SNR driven by transmitted energy ( $P \cdot \tau$ ) and noise bandwidth (B)
  - Solution: decouple the two problems by using a signal where B is not a function of  $\tau \rightarrow$  chirp
- Required altimeter performance:
  - range resolution  $\sim 50$  cm
  - implies  $\tau_c \sim 3$  ns and  $\Delta f \sim 300$  MHz
  - link budget implies compression ration  $\sim 5000$
- Implementation problems:
  - compression filter (expansion filter made by frequency multiplication)
  - video signal processing with 3 ns resolution (ADC etc. at 300 MHz)
- Solution: **Full Deramp Technique** maps relative time delay into frequency offsets.

- SeaSat introduced “full deramp”
  - recommended by Brooks and Dooley, NASA CR 1975
  - 800 km altitude
  - compressed TX pulse

$$\Delta f = f_2 - f_1 = B \frac{\Delta t}{\tau_u} = B \cdot \frac{2\Delta h}{\tau_u \cdot c}$$



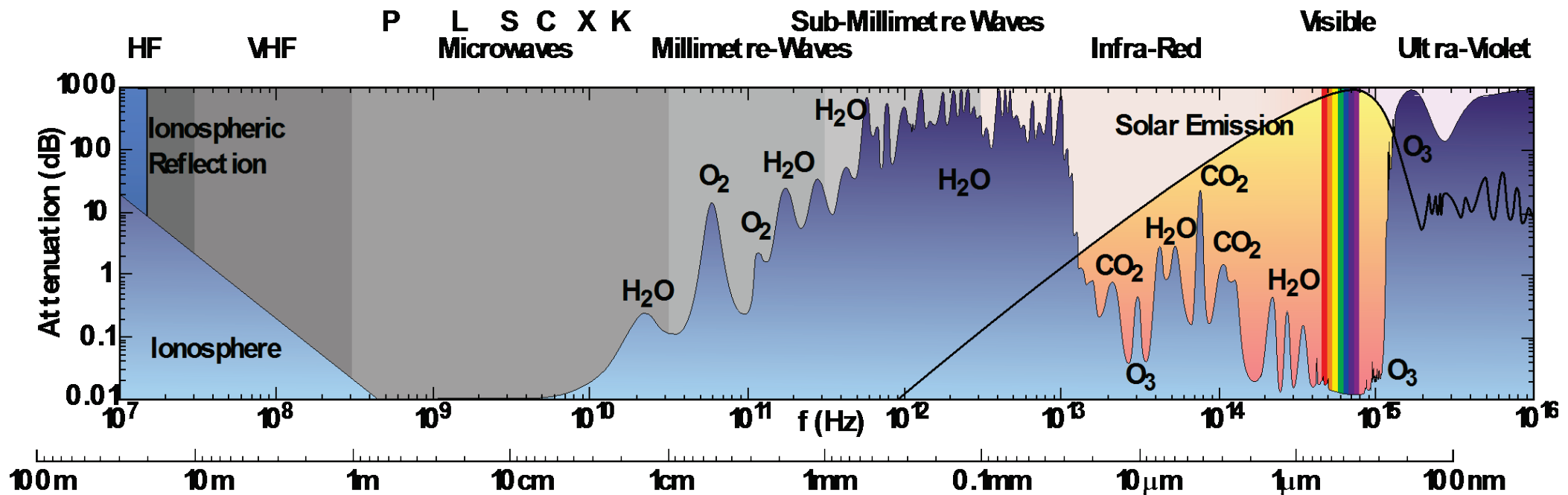


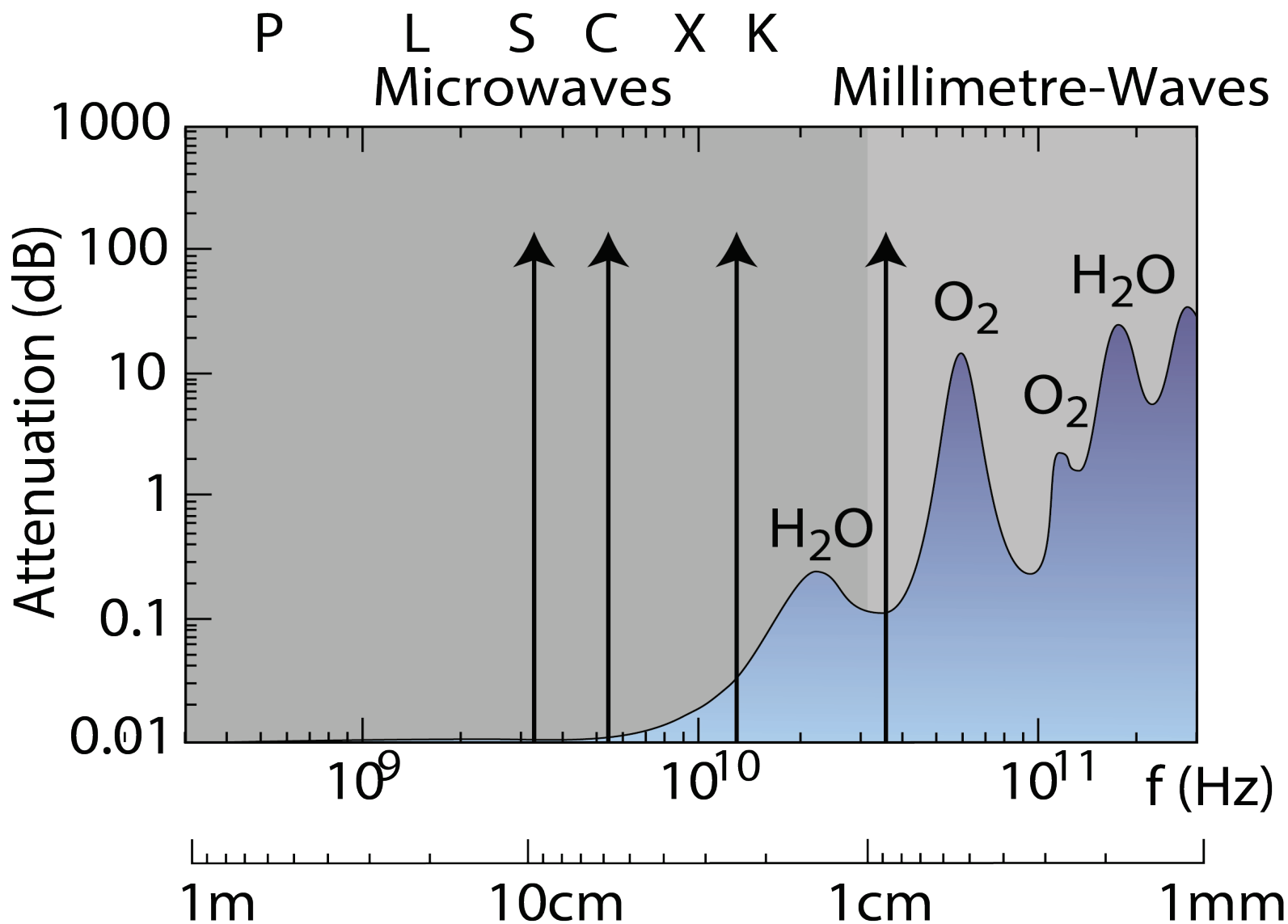
J. MacArthur, OCEANS '76

- Same chirp-generator used for TX and RX, reducing effect of phase/amplitude errors
- Transformation from time-domain to frequency-domain replaces high-frequency timing by spectrum analysis
- After deramp, timing variations have no effect
  
- Technology has radically evolved lately with Sentinel-6, and thanks to a digital architecture, a match filter has been incorporated.

# Frequencies

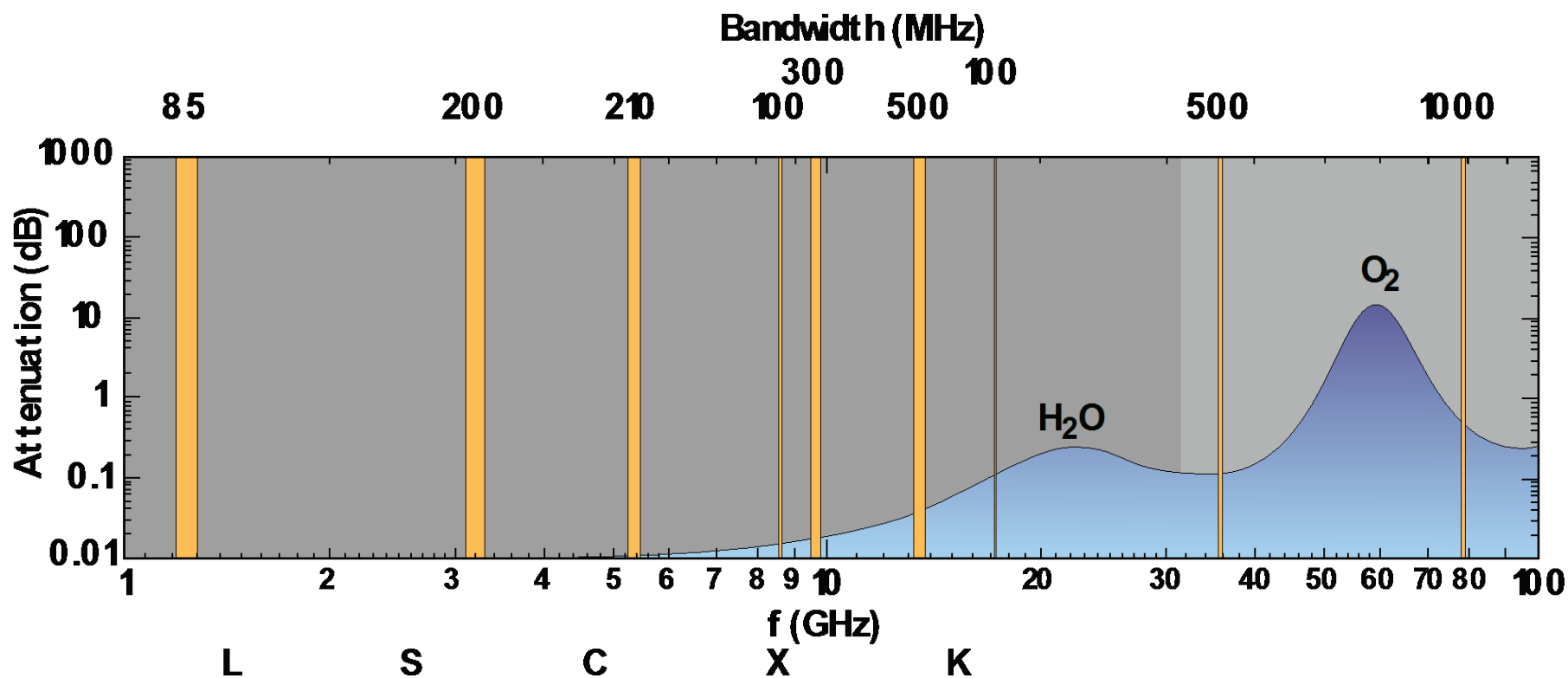
- Electromagnetic radiation only penetrates the atmosphere in a few “windows” where surface measurements can be made.
- Microwave: mature technology; not blocked by clouds.
- Optical: high spatial resolution.







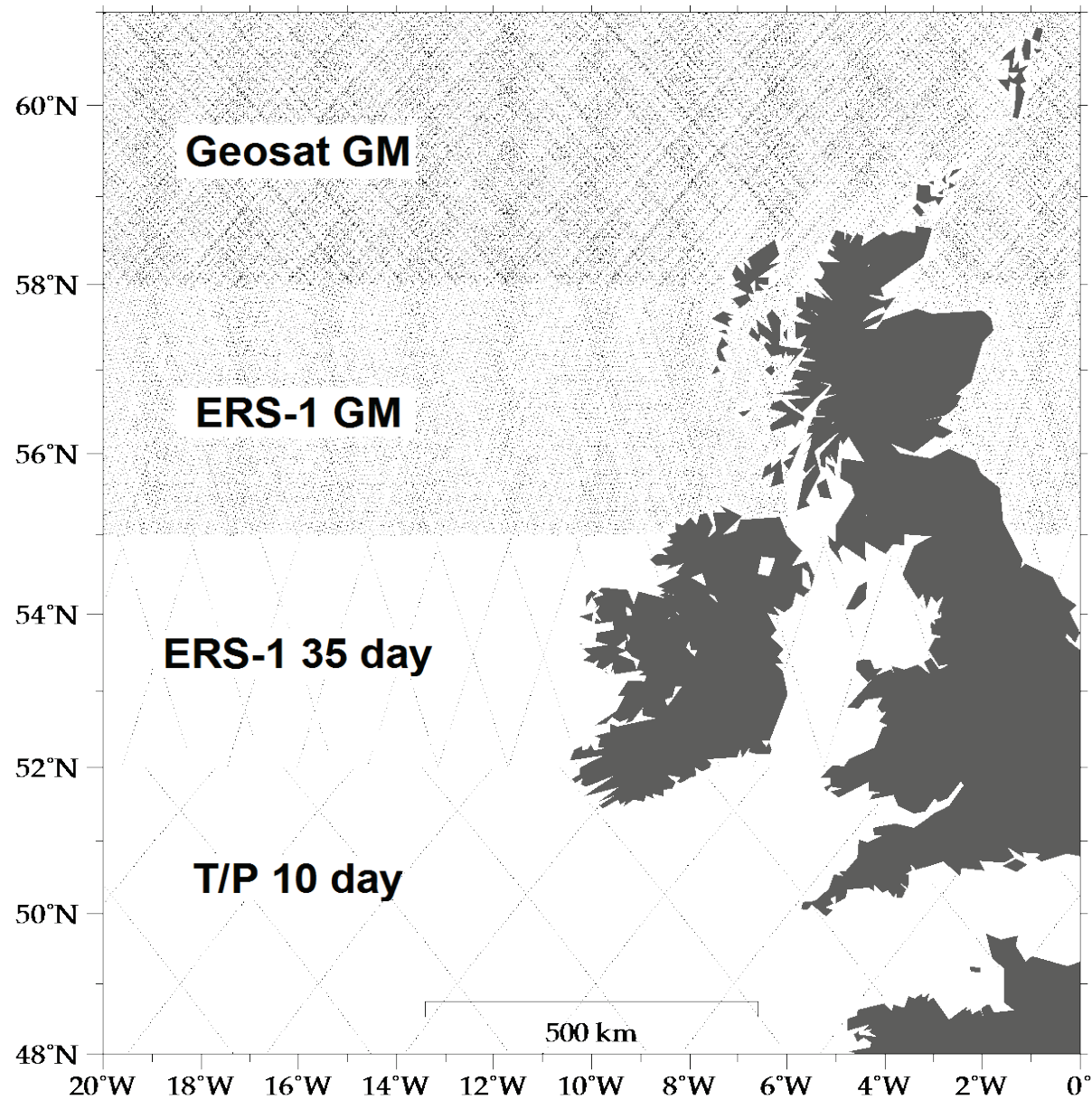
International Telecommunications Union permitted Frequency bands and bandwidths



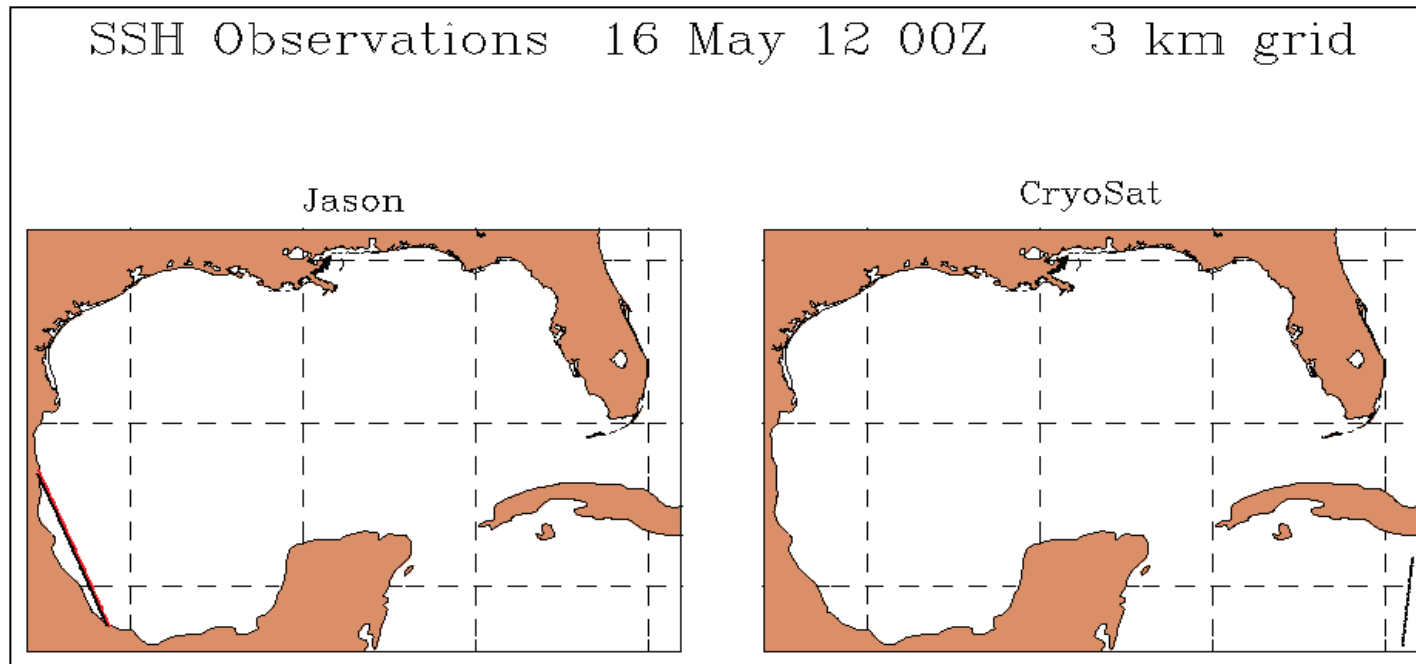
- Factors to be considered in selecting microwave frequency:
  - Reflectivity of the surface
  - Gain of antenna and its dimensions
  - Propagation loss in rain and clouds (lower frequencies are better)
  - Effect of the refractive index of ionosphere ( $\propto 1/f^2$ )
  - Available transmitter technology (less mature at millimetre waves)
  - Available frequencies and bandwidths (ITU regulations permit 9 frequency bands between 1 and 100 GHz, bandwidths 85 – 1000 MHz)
  - Decorrelation between subsequent measurements (higher frequencies decorrelate faster i.e. in a shorter time)
- Existing instruments have all used Ku-band; secondary frequencies at either C-band or S-band

# Orbits

- Altimeters now fly in 3 broad classes of orbit:
  - Oceanography “reference” orbit:
    - 1336 km altitude
    - 66° inclination
    - 10-day repeat cycle
  - “complementary” orbit:
    - ~800 km altitude
    - ~98° inclination (sun-synchronous)
    - repeat cycle 29 or 35 days
  - “geodetic” orbits (several)
    - long repeat period

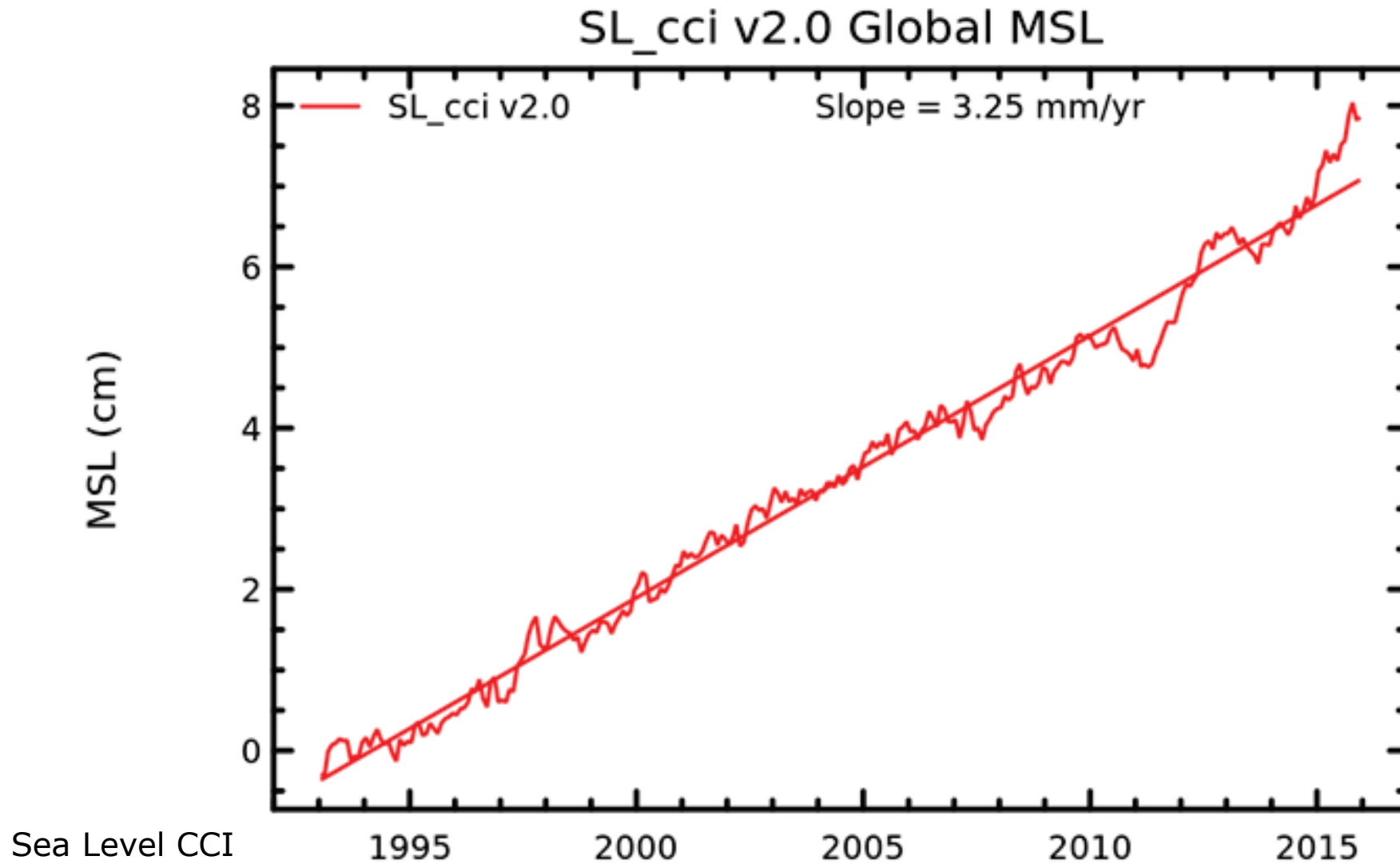


Courtesy of R. Cullen

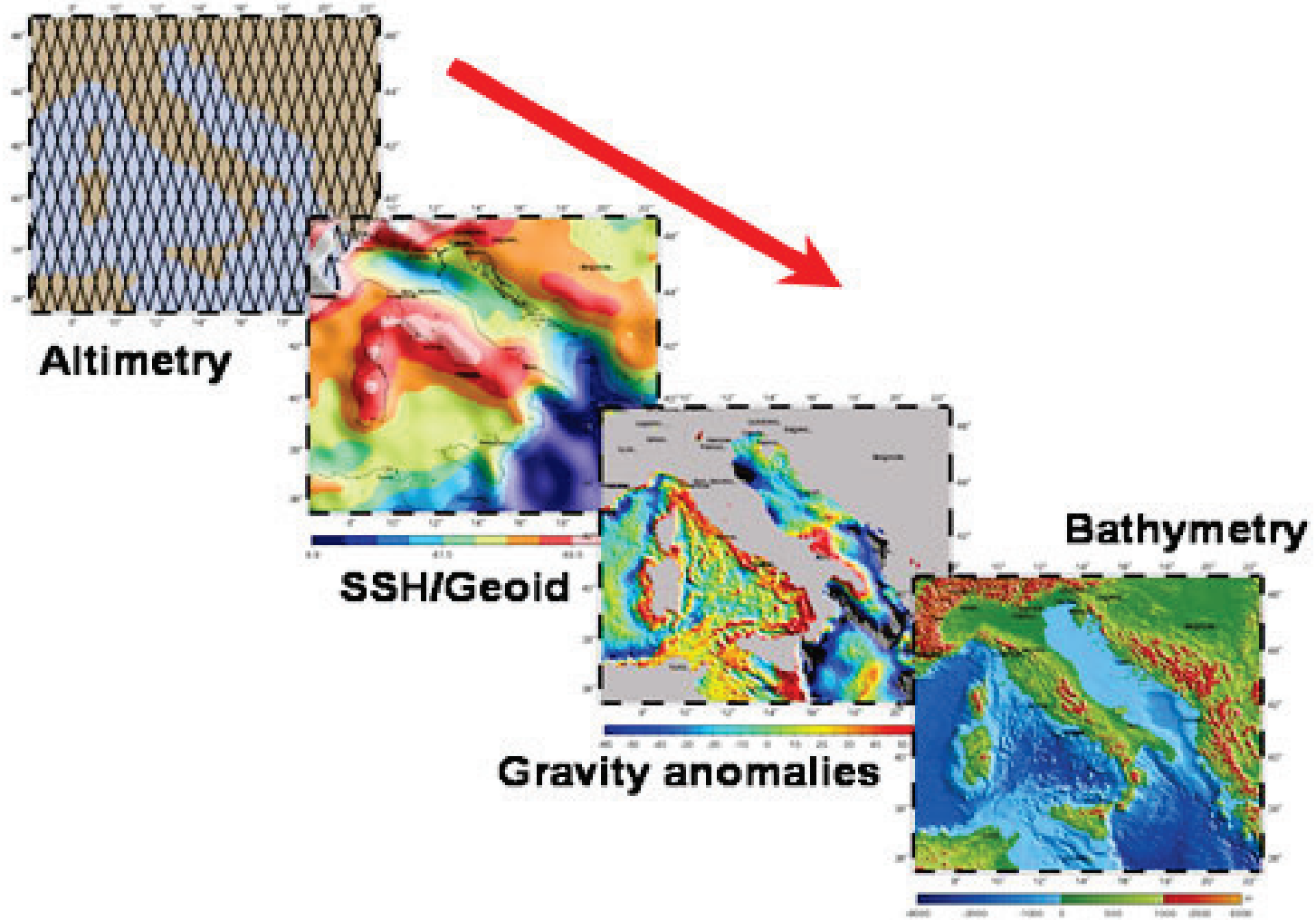


G. Jacobs, US Navy

# Applications



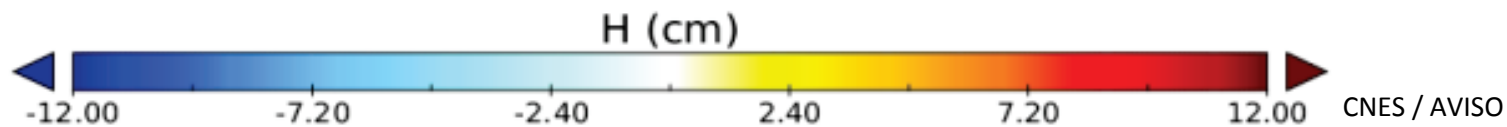
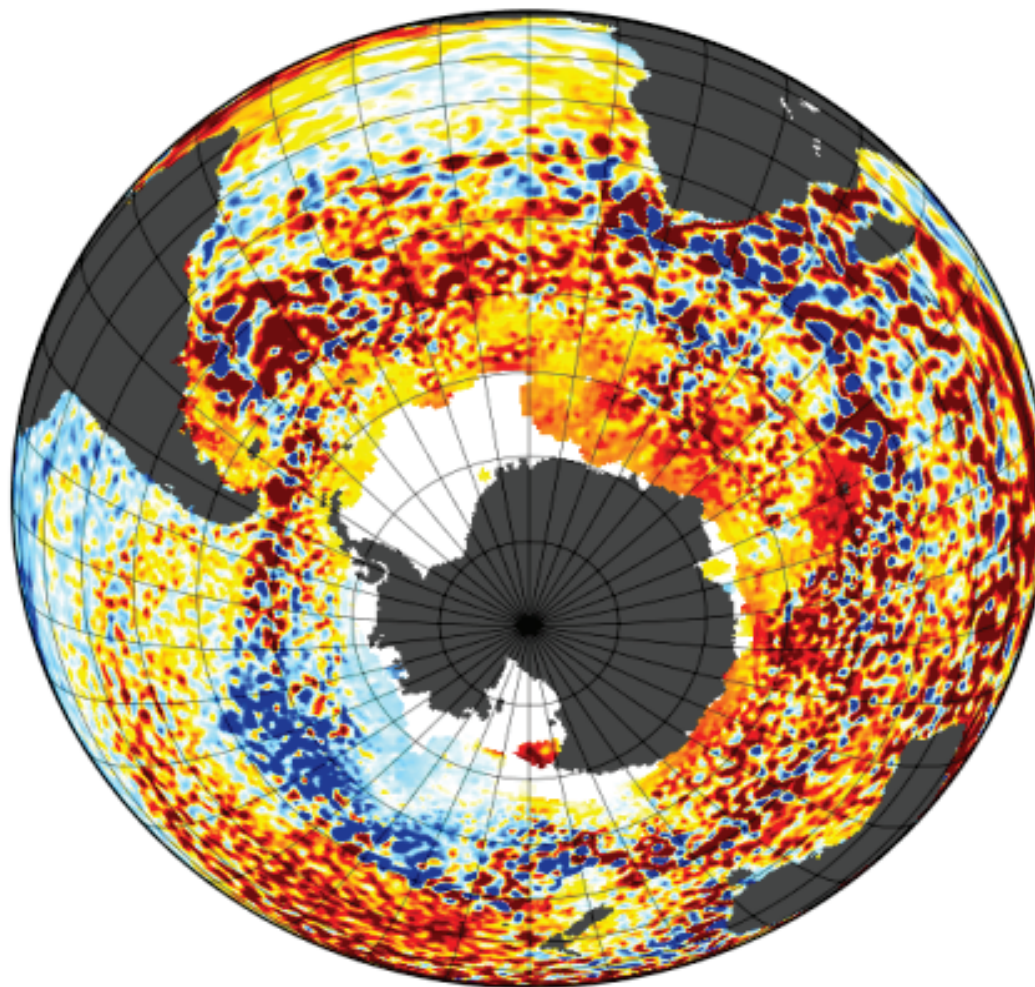


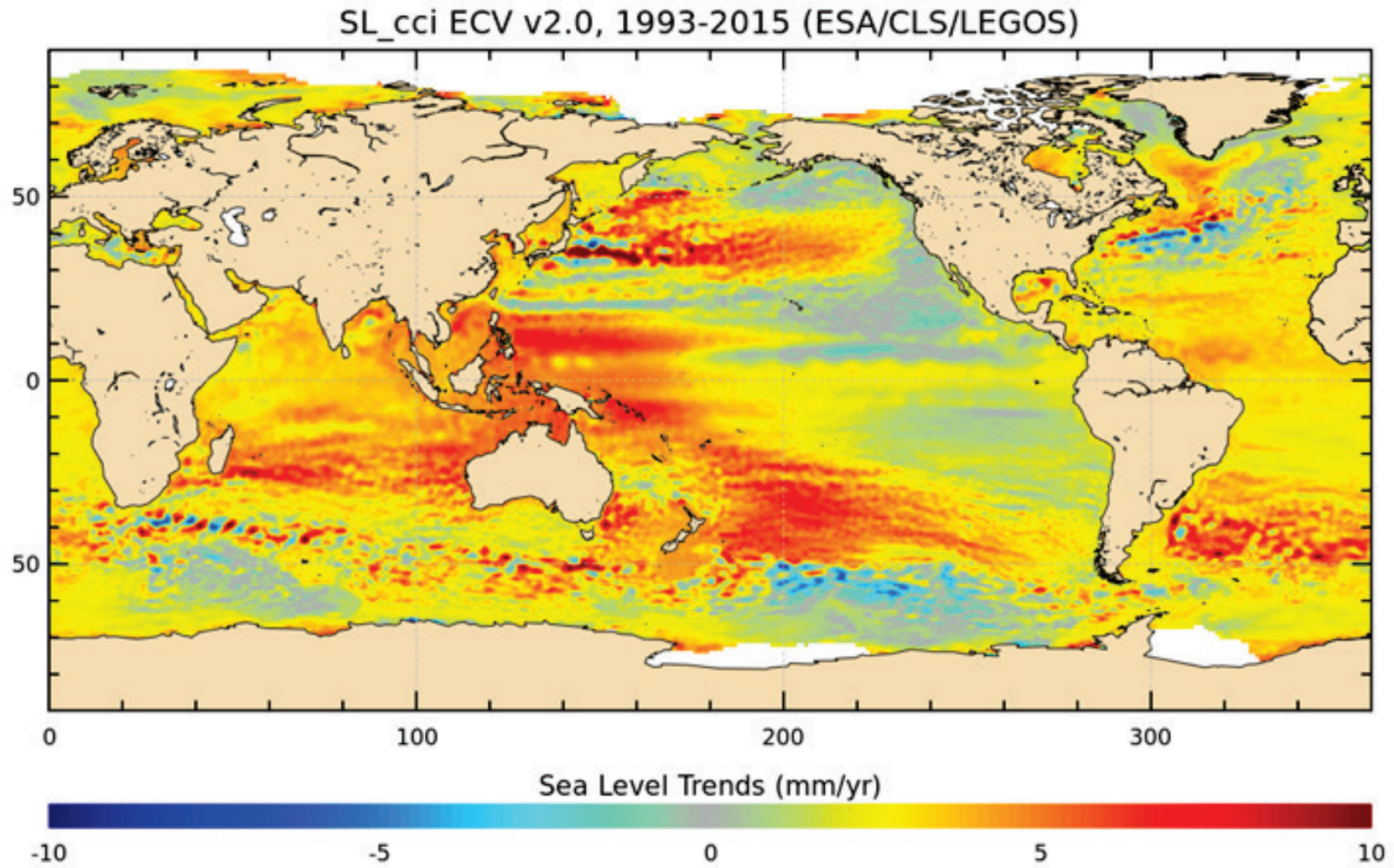


## Global multi-mission map of sea level anomaly - 1st January 2012

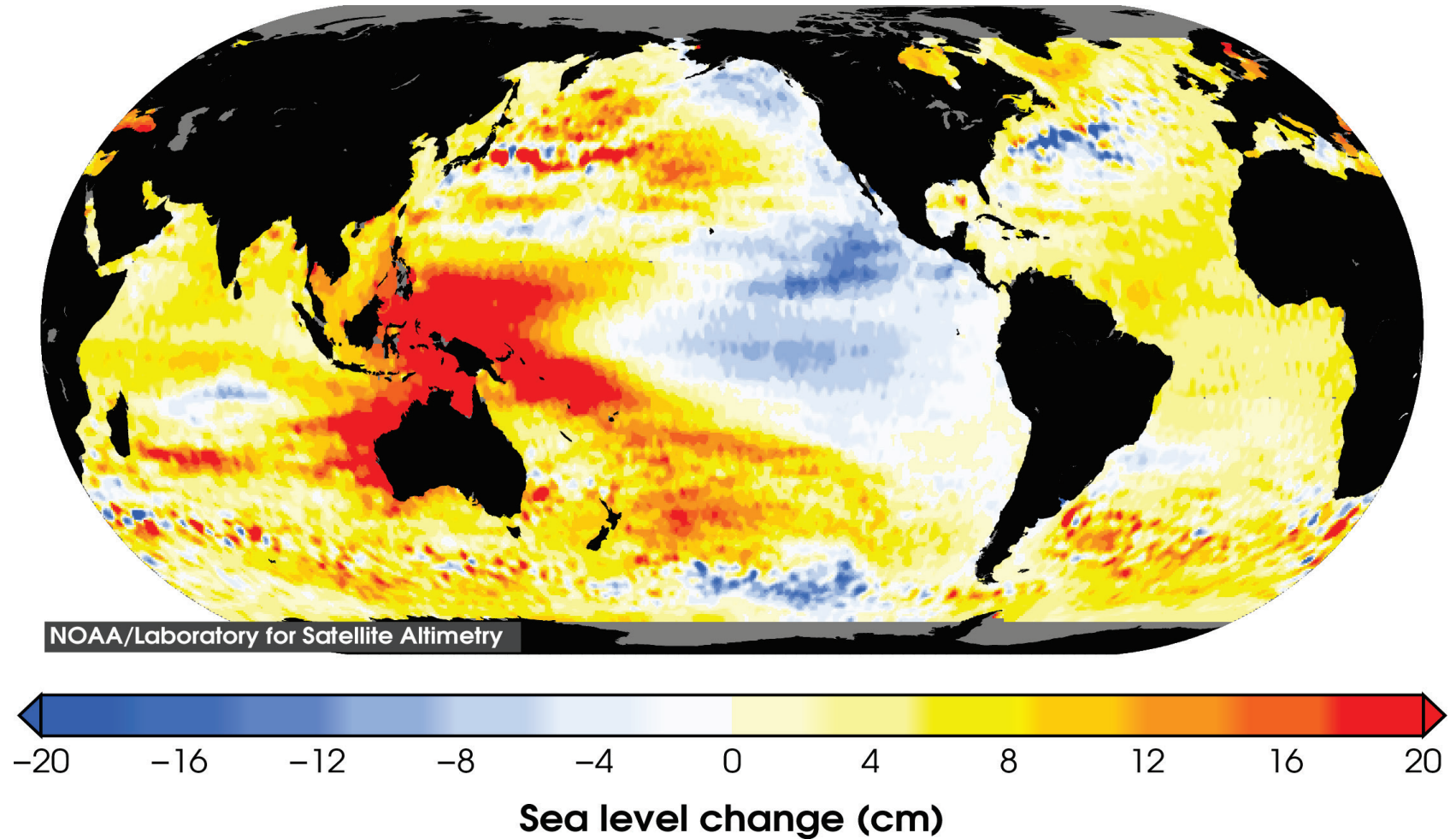
(Jason-2, Jason-1, Envisat, Cryosat-2)

Sea Level Anomaly is the deviation of ocean height from the mean due to variability in the ocean circulation patterns

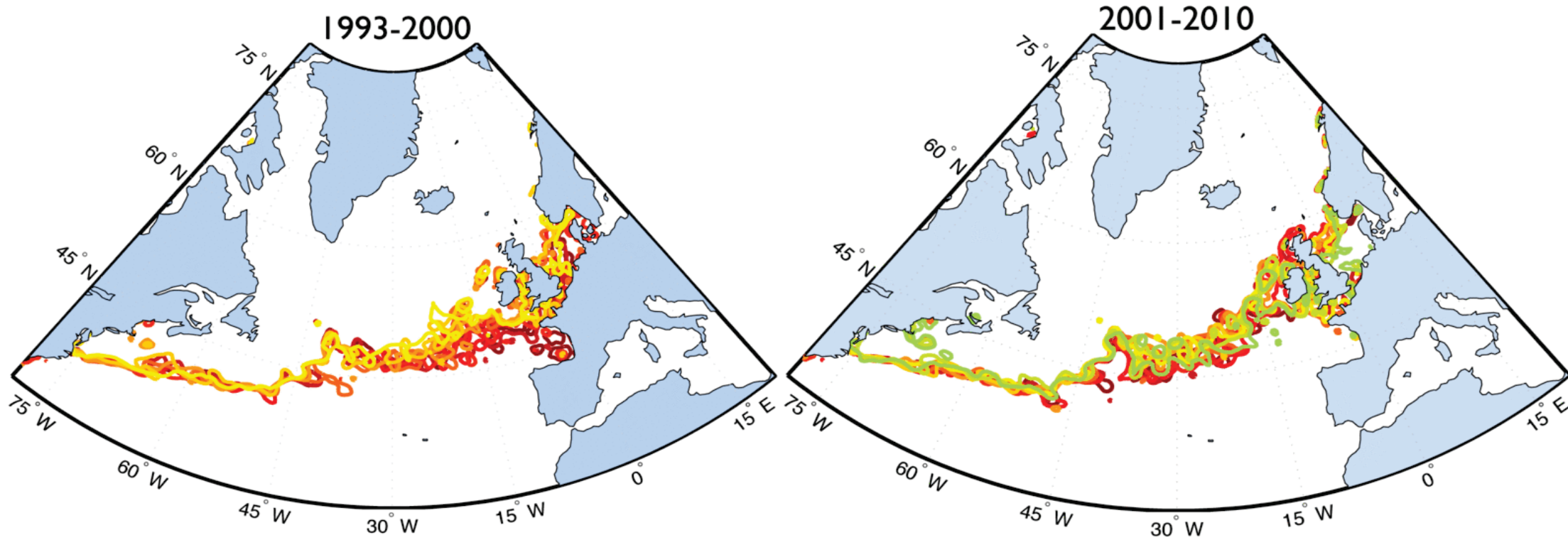




Sea Level CCI



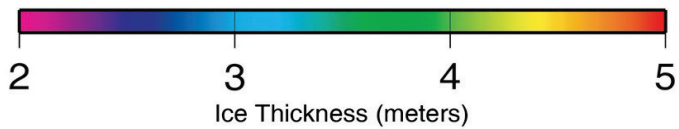
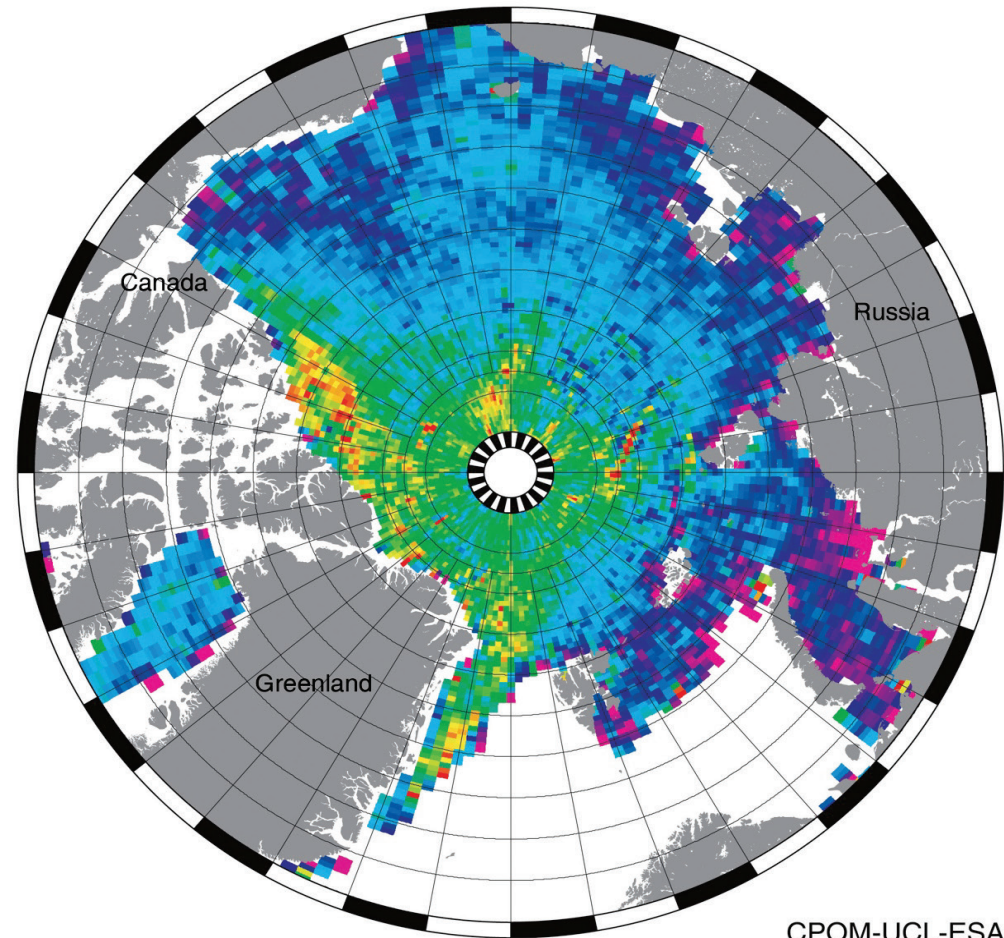
Variations due to changing heat content and winds



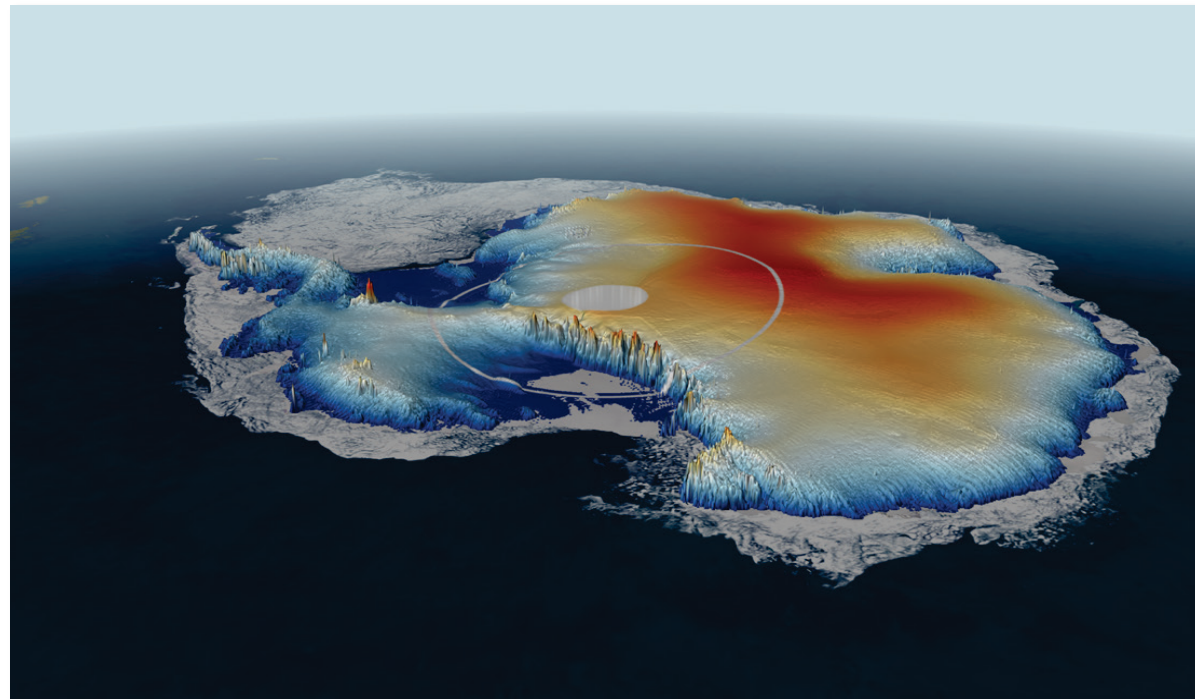
L. Chafik, Stockholm University

### Sea ice thickness in the Arctic ocean

(January/February 2011)

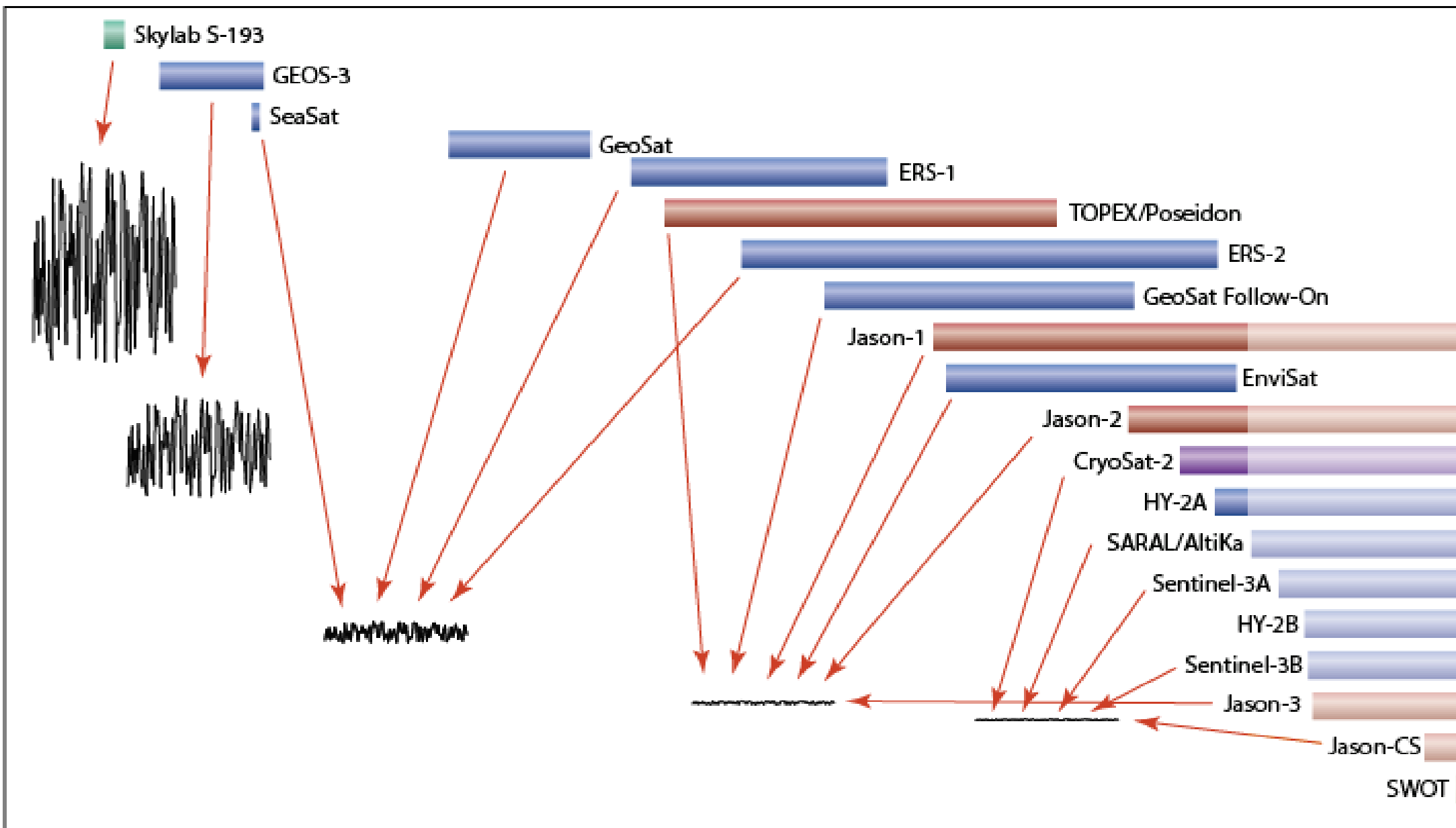


### Antarctic Topography

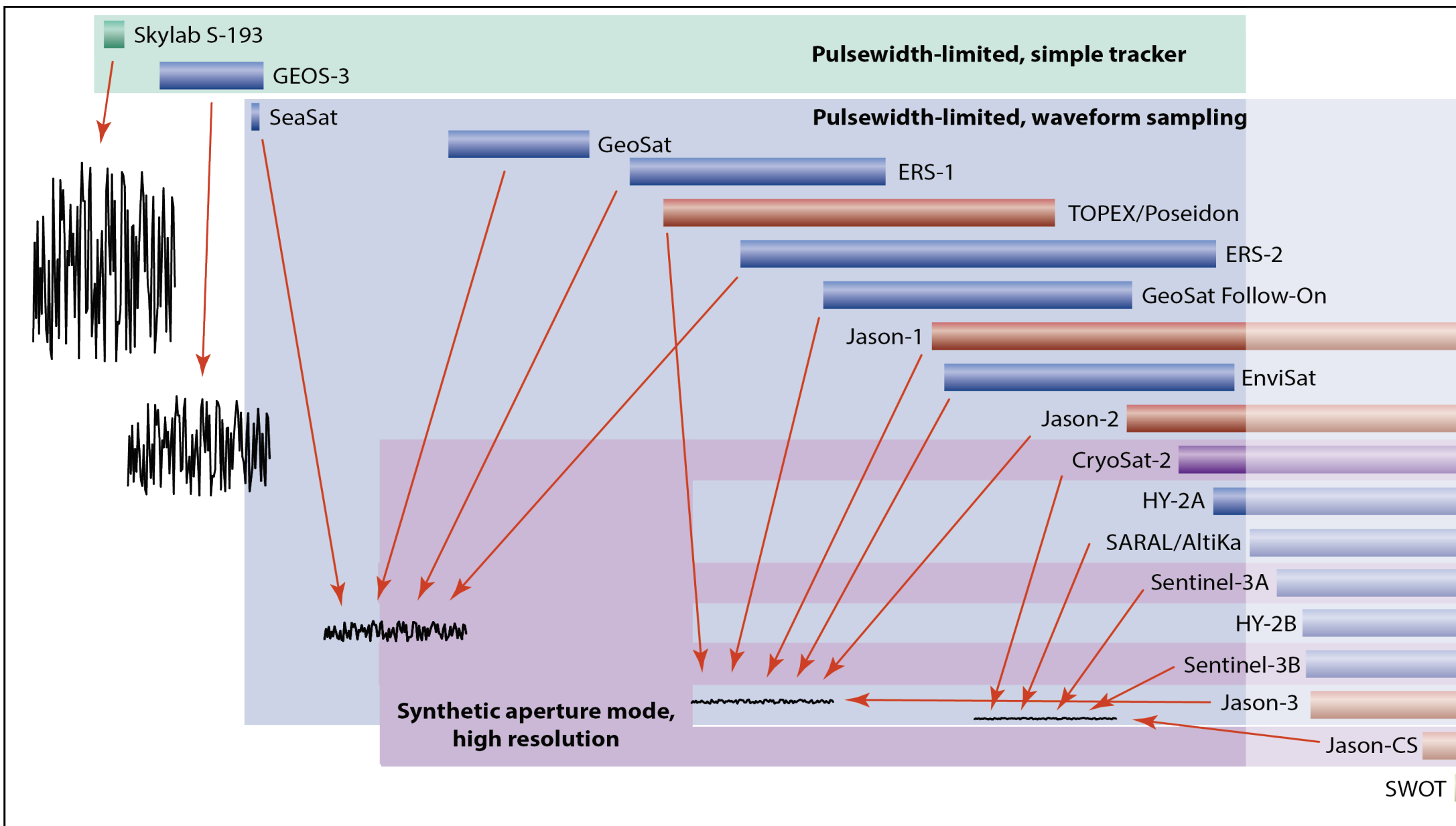


CPOM/UCL/ESA/Planetary Visions

# Current missions: High resolution modes







- **CryoSat: SIRAL**
  - high resolution Synthetic Aperture mode
  - interferometer
- **Sentinel-3: SRAL**
  - high resolution Synthetic Aperture mode
- **AltiKa: SARAL**
  - High-frequency pulse-width limited
  - Ka-band
  - integrated microwave radiometer
  - increased bandwidth: increased resolution
- **Sentinel-6/Jason-CS: Poseidon-4**
  - conventional Ku-band and C-band
  - multiple new technologies
- **SWOT**
  - wide-swath, Ka-band system

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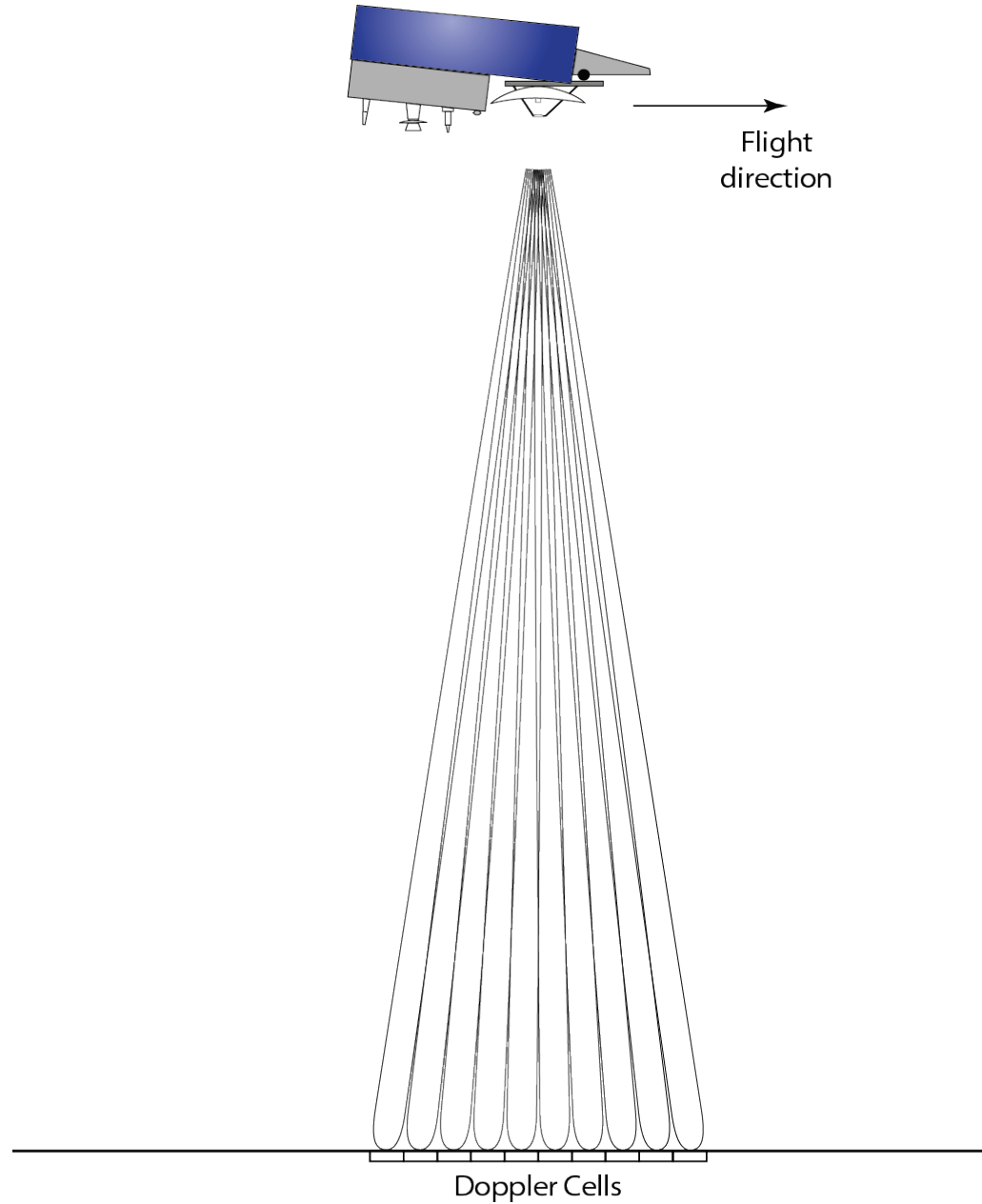
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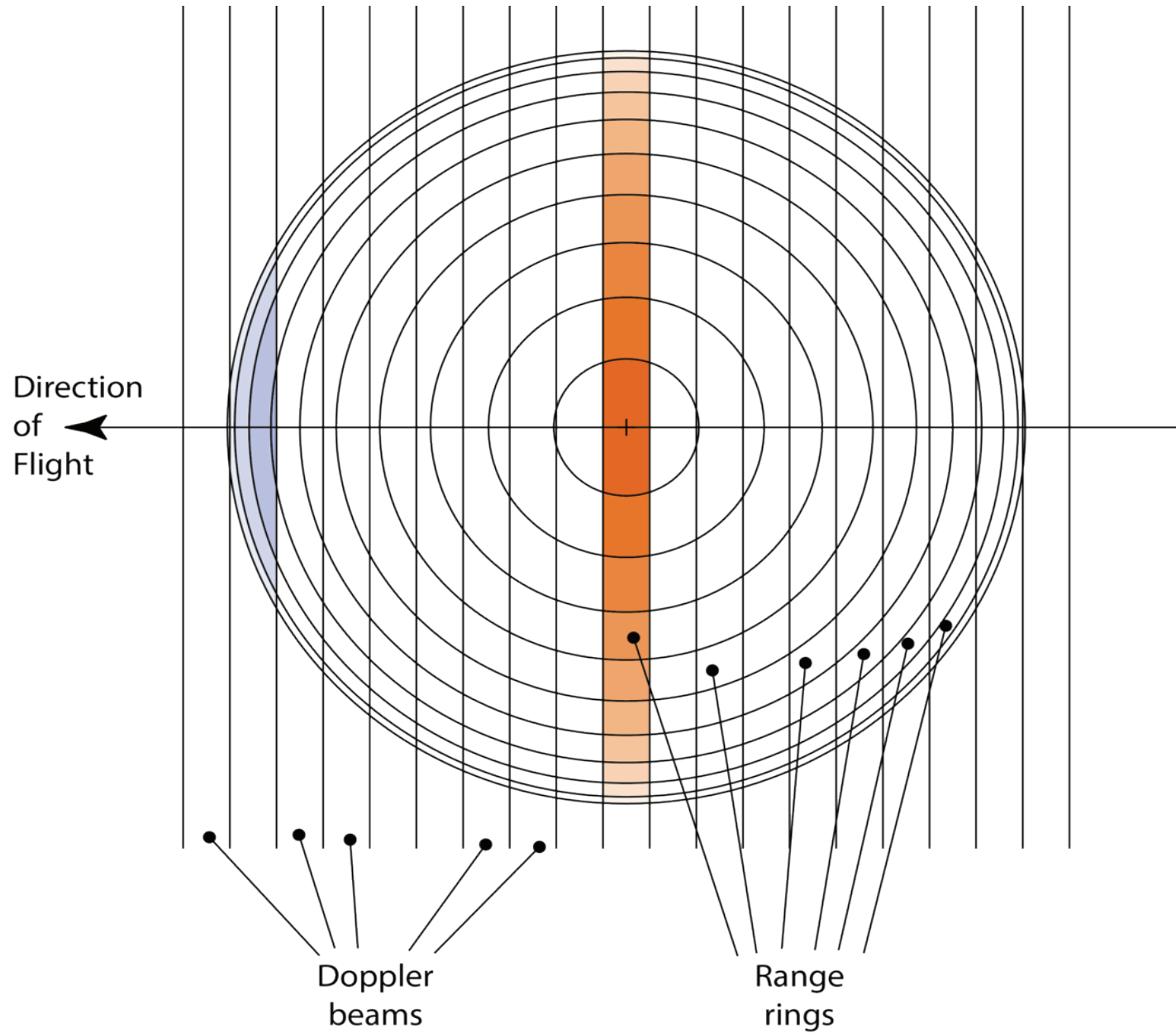
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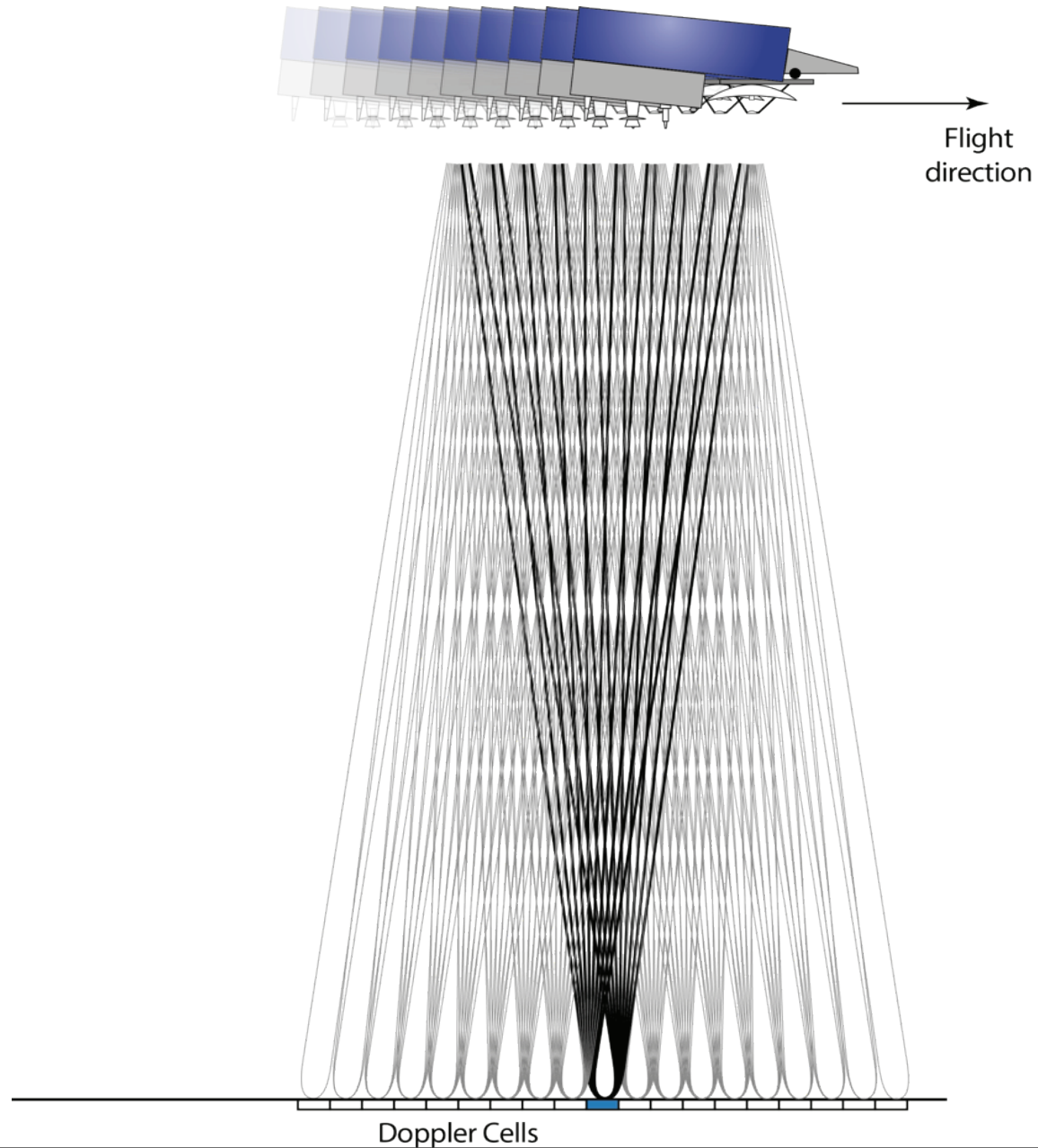


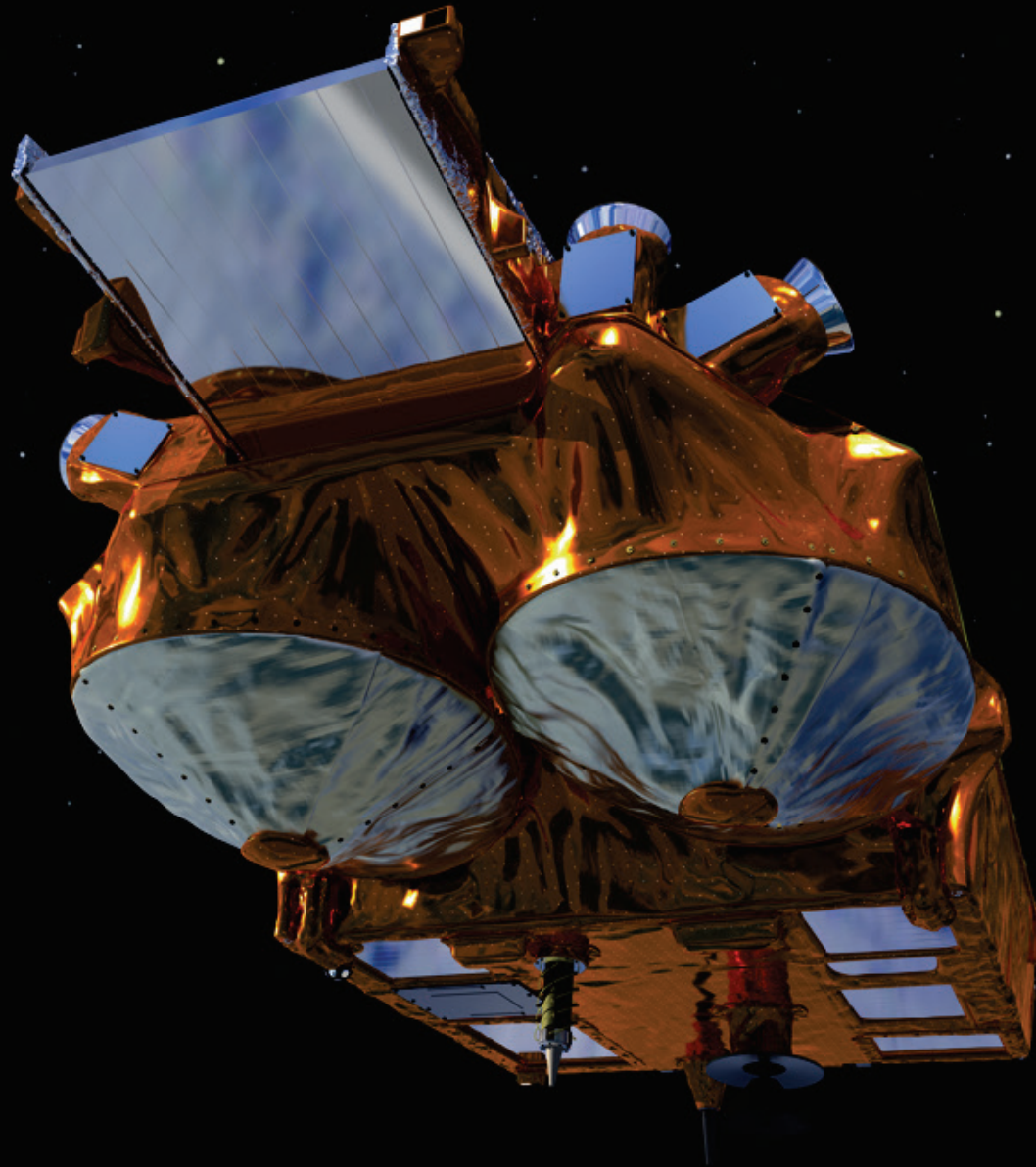
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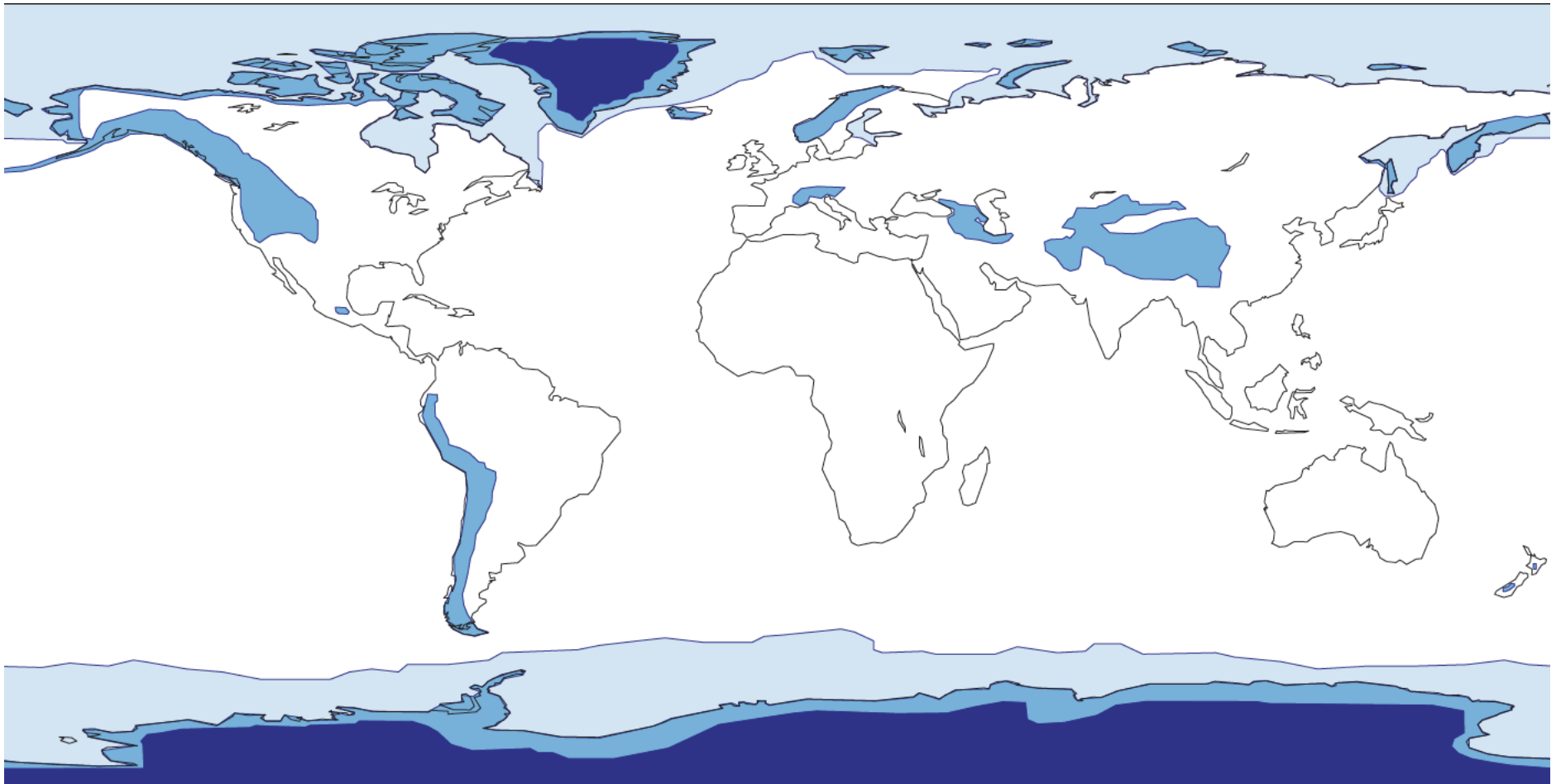


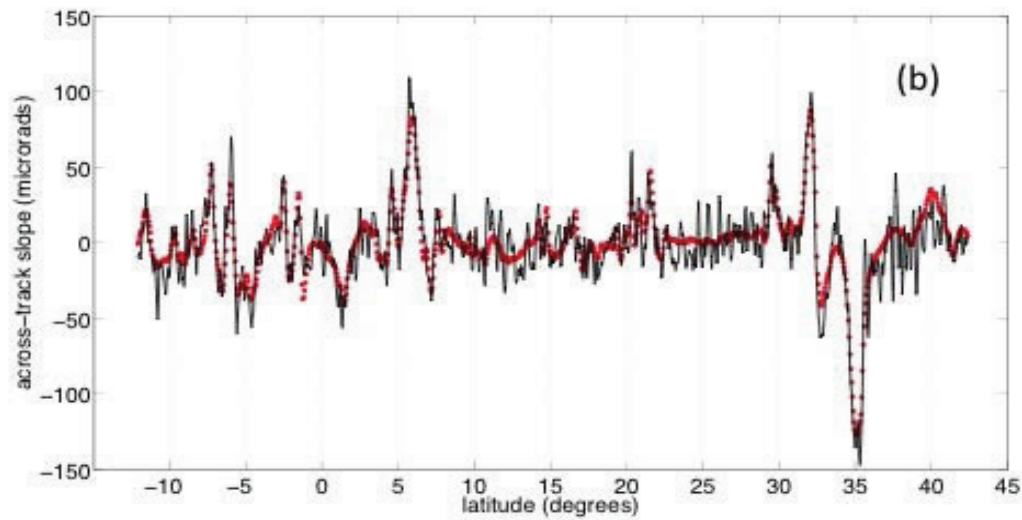
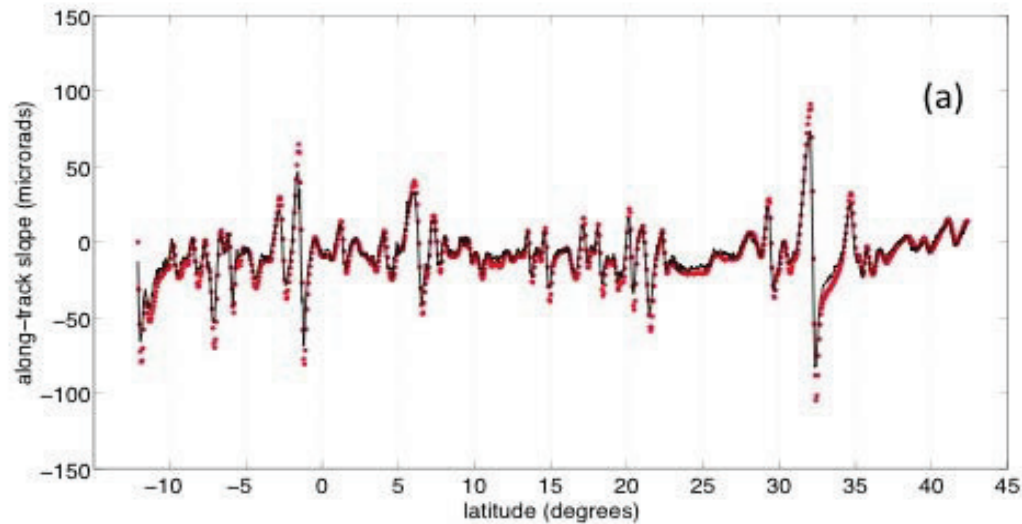






The medium shaded areas are regions of high surface slope – these are being measured using the SARin mode.





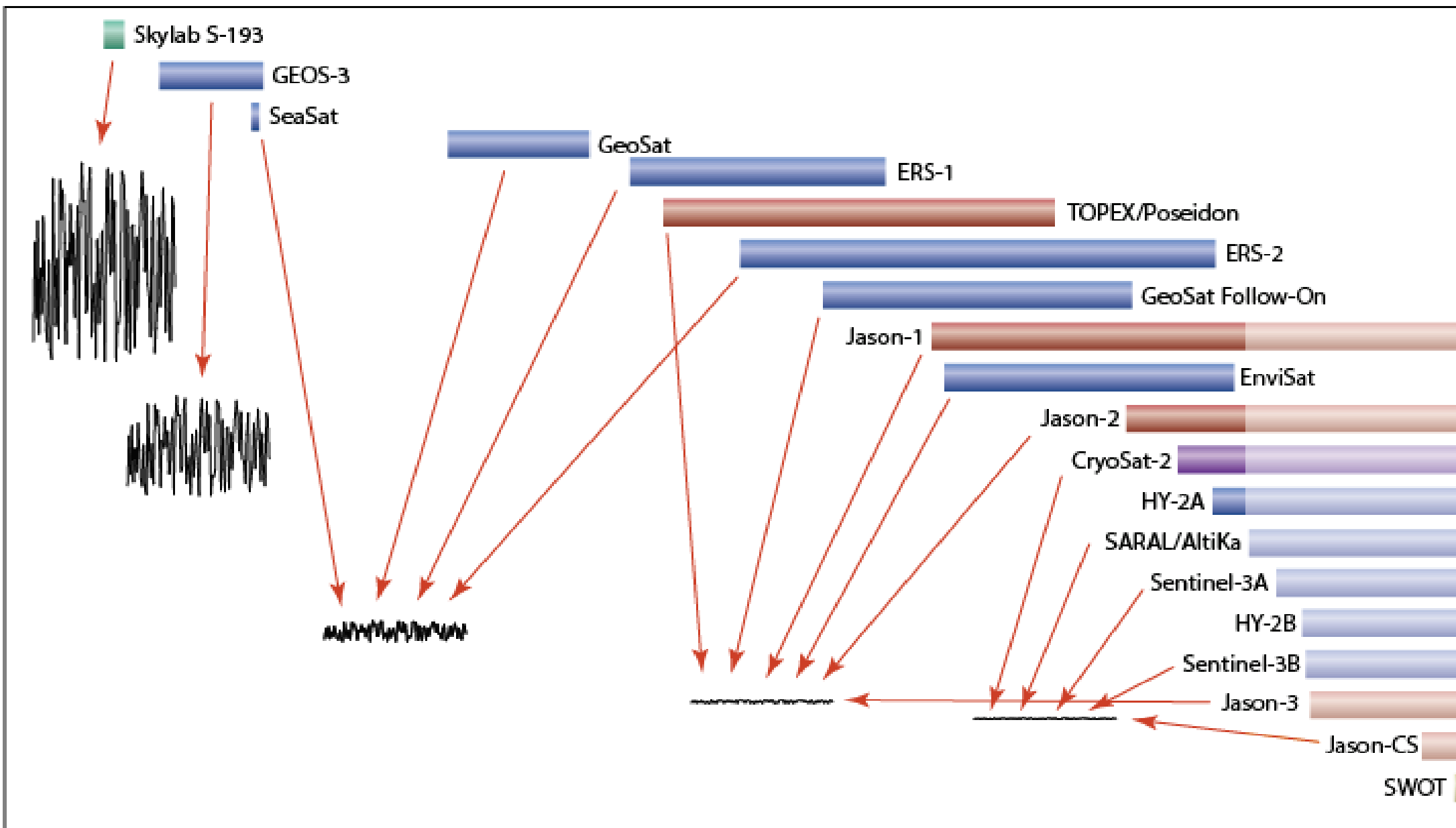
Black: SIRAL  
Red: EGM08

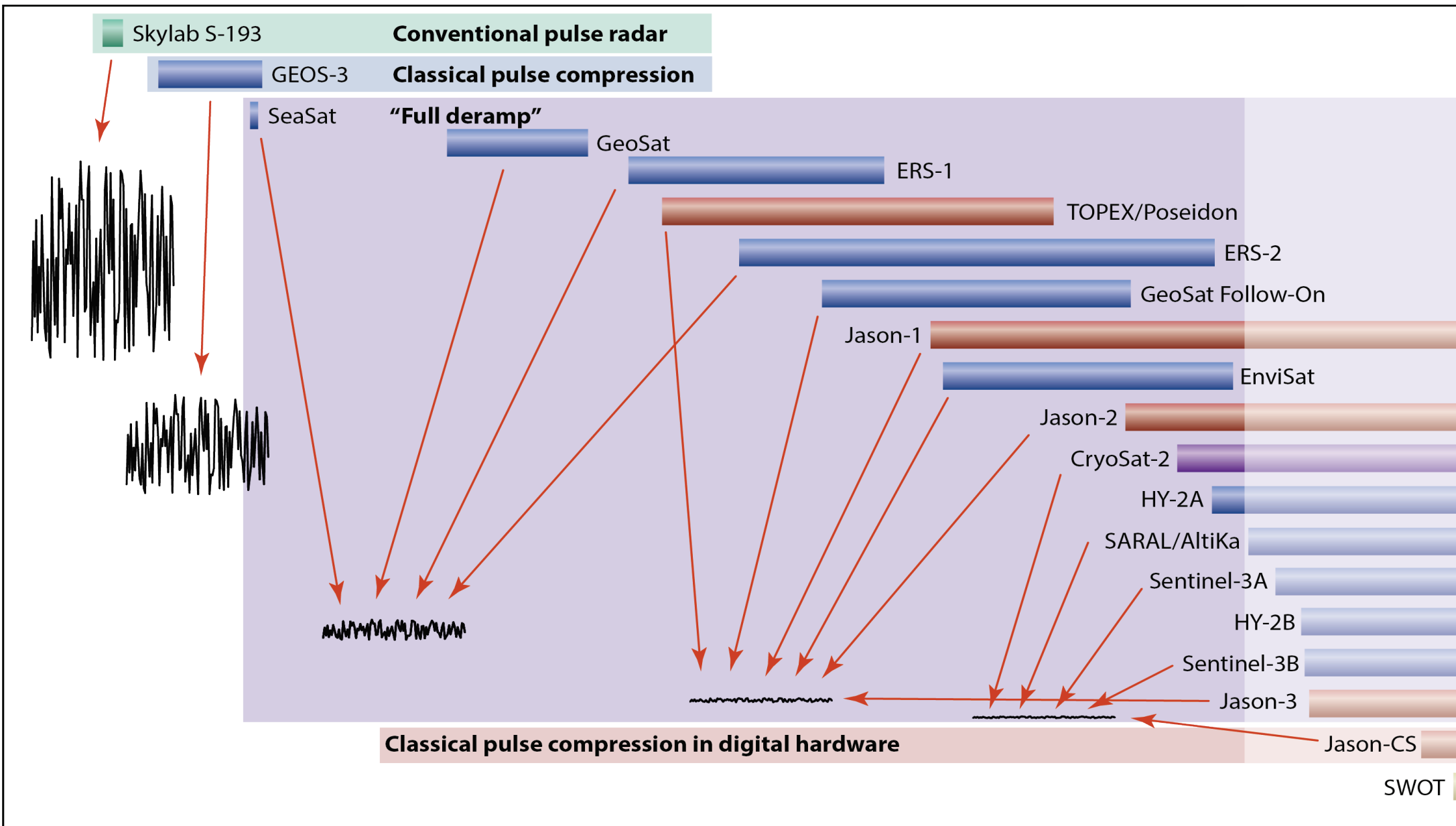
UCL/ESA/NOAA

## 2-D Ocean Surface Gradient from Interferometry

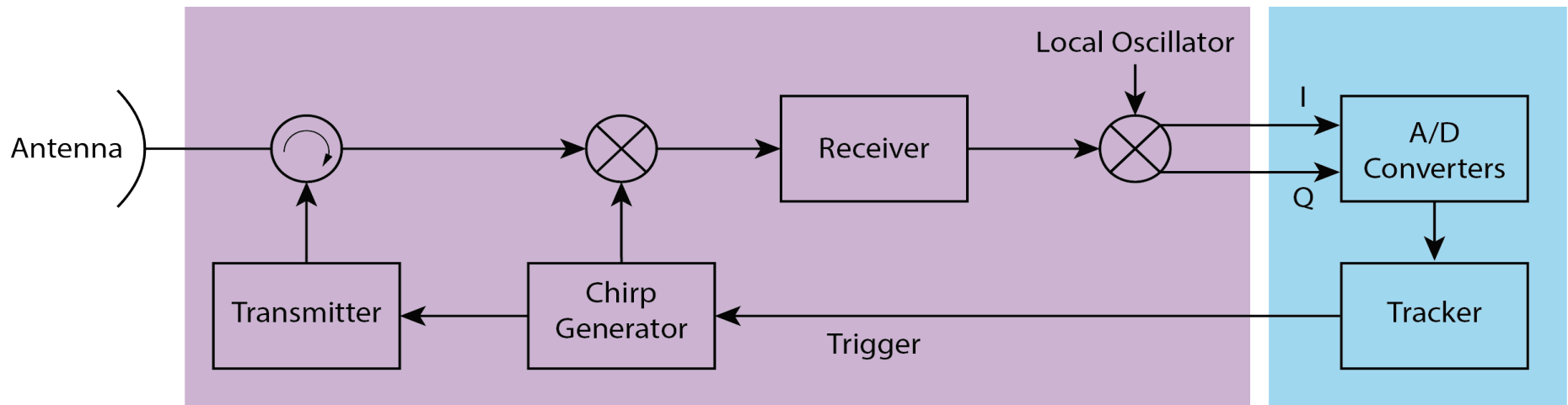


# Newest developments

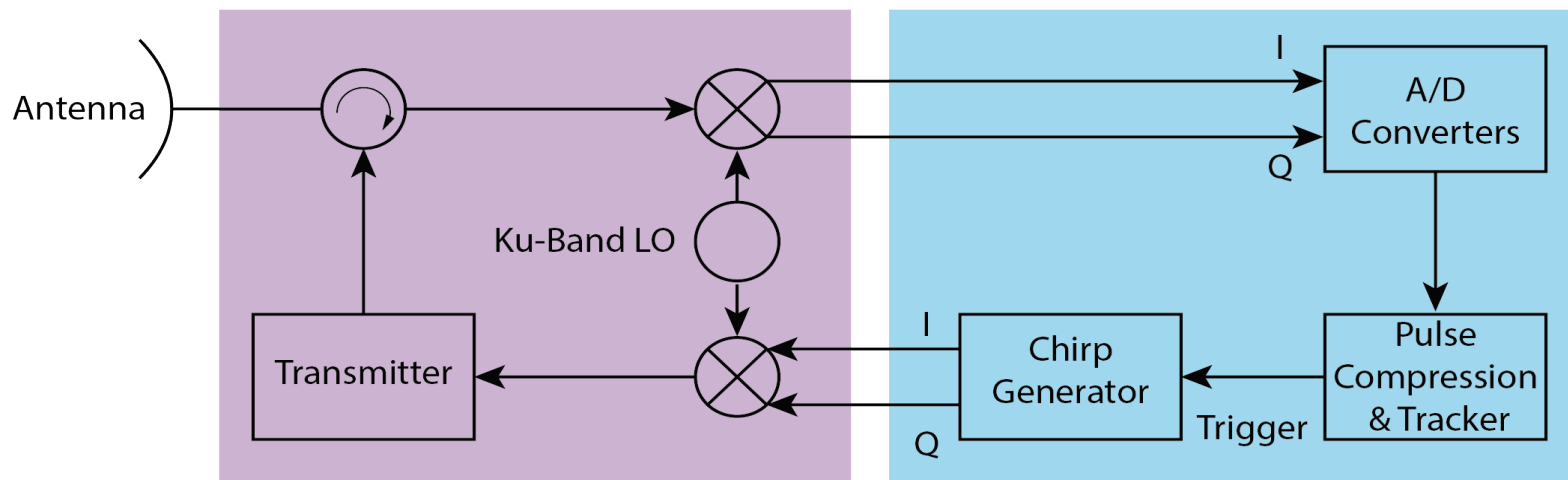




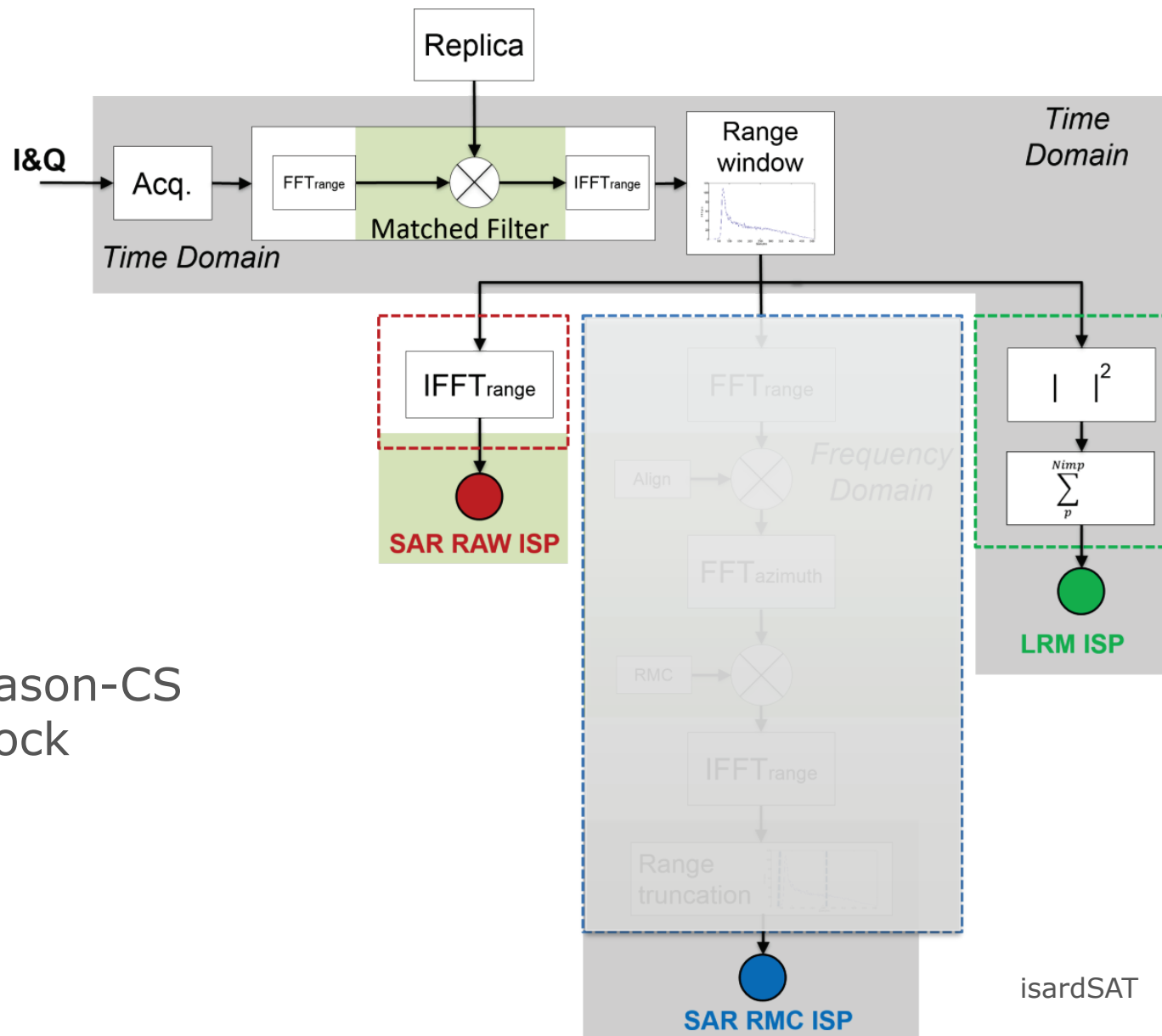
- Original SeaSat (1978) concept of full deramp used by all subsequent altimeters
- Boundary between digital and RF hardware continually evolved
- Chirp generator required frequency multiplication (analog or digital)



**SeaSat**



**Sentinel-6/Jason-CS**



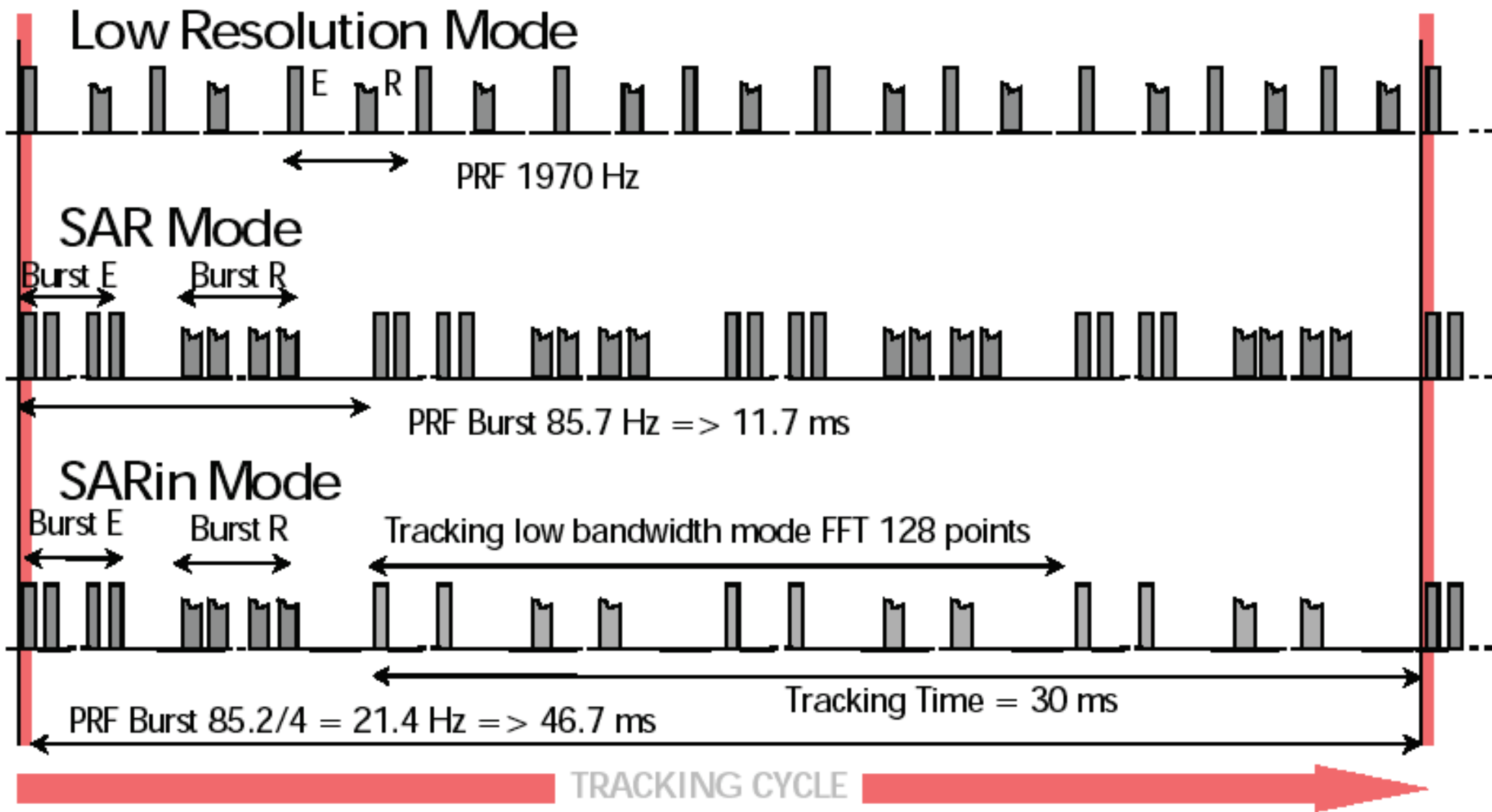
Sentinel-6/Jason-CS high level block diagram

# Chronograms





Thales Alenia Space

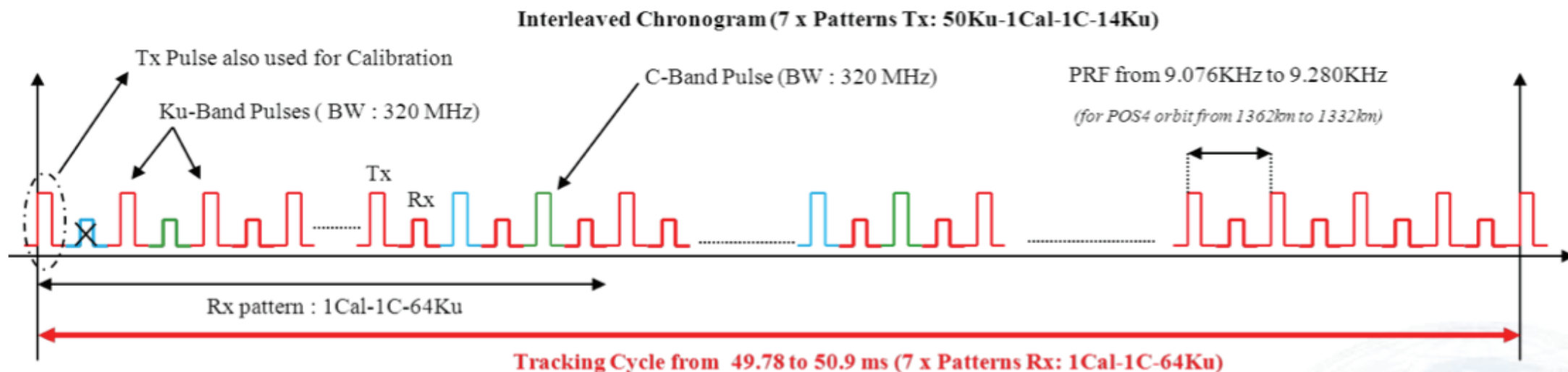


- A further mode is under development o Thales Alenia Space for Sentinel-6/Jason-CS:
  - continuous transmission of pulses at  $\sim 9$  kHz
  - receive window between each transmitted pulse
  - requires adaptive PRF to accommodate altitude changes
  - 1 out of  $n$  pulses is a C-band pulse
- Enables simultaneous SAR and LRM operation

## Sentinel-6/J-CS Interleaved

- PRF  $\sim 9$  KHz      Careful with Doppler ambiguities !

PRF (or PRI) changes around the orbit.  
PRF constant in reception.



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# Conclusions

- Altimetry from space has been used for almost 40 years and continuously since 1991
- Its original promise has been realised and exceeded
- Today it is a vital tool in operational oceanography
- New techniques, under development now, will enable improved performance in the future.

Thank you !